

LA library  
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# Chapter 1

## Class Index

### 1.1 Class Hierarchy

This inheritance list is sorted roughly, but not completely, alphabetically:

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LA::NRMat< T > . . . . .	6
LA::NRMat_from1< T > . . . . .	45
LA::NRMat< T > . . . . .	6
LA::NRSMat< T > . . . . .	47
LA::NRSMat< T > . . . . .	47
LA::NRSMat_from1< T > . . . . .	65
LA::NRVec< T > . . . . .	66
LA::NRVec< bitvector_block > . . . . .	66



# Chapter 2

## Class Index

### 2.1 Class List

Here are the classes, structs, unions and interfaces with brief descriptions:

<a href="#">LA::gencmp&lt; T, type &gt;</a> (!! gencmp's and genswap are critical for performance, make sure that compiler really inlines them ) . . . . .	5
<a href="#">LA::NRMat&lt; T &gt;</a> (NRMat<T> class template implementing the matrix interface ) . . . . .	6
<a href="#">LA::NRMat_from1&lt; T &gt;</a> . . . . .	45
<a href="#">LA::NRSMat&lt; T &gt;</a> . . . . .	47
<a href="#">LA::NRSMat_from1&lt; T &gt;</a> . . . . .	65
<a href="#">LA::NRVec&lt; T &gt;</a> (NRVec<T> class template implementing the vector interface ) . . . . .	66





# Chapter 3

## Class Documentation

### 3.1 LA::gencmp< T, type > Struct Template Reference

!! gencmp's and genswap are critical for performance, make sure that compiler really inlines them

#### Static Public Member Functions

- static SPMatindexdiff EXEC (register const SPMatindex i, register const SPMatindex j)

#### 3.1.1 Detailed Description

**template<class T, int type> struct LA::gencmp< T, type >**

!! gencmp's and genswap are critical for performance, make sure that compiler really inlines them

The documentation for this struct was generated from the following file:

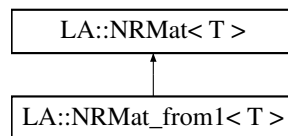
- sparsemat.cc

## 3.2 LA::NRMat< T > Class Template Reference

[NRMat<T>](#) class template implementing the matrix interface.

```
#include <mat.h>
```

Inheritance diagram for LA::NRMat< T >::



### Public Member Functions

- [~NRMat](#) ()  
*standard destructor*
- [NRMat](#) ()  
*inlined constructor creating zero matrix of general type T*
- [NRMat](#) (const int n, const int m, const GPUID loc=undefined)  
*Inlined constructor creating matrix of given size and location. Because of performance reasons, no initialization is done.*
- [NRMat](#) (const T &a, const int n, const int m, const GPUID loc)  
*inlined constructor creating matrix of given size filled with prescribed value and stored at given location*
- [NRMat](#) (const T &a, const int n, const int m)  
*inlined constructor creating matrix of given size filled with prescribed value*
- [NRMat](#) (const T \*a, const int n, const int m)  
*inlined constructor creating matrix of given size filled with data located at given memory location*
- [NRMat](#) (const [NRMat](#) &rhs)  
*inlined copy-constructor*
- [NRMat](#) (const typename LA\_traits\_complex< T >::NRMat\_Noncomplex\_type &rhs, bool imag-part=false)  
*complexifying constructor*
- [NRMat](#) (const [NRSMat](#)< T > &rhs)  
*explicit constructor converting symmetric matrix stored in packed form into a [NRMat](#)<T> object*
- [NRMat](#) (const [NRVec](#)< T > &rhs, const int n, const int m, const int offset=0)  
*explicit constructor converting vector into a [NRMat](#)<T> object*
- const bool **operator!=** (const [NRMat](#) &rhs) const
- const bool **operator==** (const [NRMat](#) &rhs) const

- int `getcount` () const  
*determine the count of references to this object*
- void `copyonwrite` ()  
*ensure that the data of this matrix are referenced exactly once*
- GPUID `getlocation` () const
- void `moveto` (const GPUID dest)
- void `randomize` (const typename LA\_traits< T >::normtype &x)  
*fill the matrix with pseudorandom numbers (uniform distribution)*
- NRMat & `operator=` (const NRMat &rhs)  
*assignment operator performing shallow copy*
- NRMat & `operator|=` (const NRMat &rhs)  
*assignment operator performing deep copy*
- NRMat & `operator=` (const T &a)  
*assign scalar value to the diagonal elements*
- NRMat & `operator+=` (const T &a)  
*add scalar value to the diagonal elements*
- NRMat & `operator-=` (const T &a)  
*subtract scalar value to the diagonal elements*
- NRMat & `operator*=` (const T &a)  
*multiply by a scalar value*
- NRMat & `operator+=` (const NRMat &rhs)  
*add given matrix*
- NRMat & `operator-=` (const NRMat &rhs)  
*subtract given matrix*
- NRMat & `operator^=` (const NRMat< T > &rhs)  
*Hadamard element-wise product.*
- NRMat & `operator+=` (const NRSMat< T > &rhs)  
*add symmetric matrix stored in packed form*
- NRMat & `operator-=` (const NRSMat< T > &rhs)  
*subtract symmetric matrix stored in packed form*
- const NRMat `operator-` () const  
*unary minus*
- const NRMat `operator+` (const T &a) const  
*add scalar value to all matrix elements and return the result by value*

- `const NRMat operator-` (`const T &a`) `const`  
*subtract scalar value from all matrix elements and return the result by value*
- `const NRMat operator*` (`const T &a`) `const`  
*multiply all matrix elements by a scalar value and return the result by value*
- `const NRMat operator+` (`const NRMat &rhs`) `const`  
*add given matrix and return the result by value*
- `const NRMat operator+` (`const NRSMat< T > &rhs`) `const`  
*add given symmetric matrix stored in packed form and return the result by value*
- `const NRMat operator-` (`const NRMat &rhs`) `const`  
*subtract given matrix and return the result by value*
- `const NRMat operator-` (`const NRSMat< T > &rhs`) `const`  
*subtract given symmetric matrix stored in packed form and return the result by value*
- `const NRMat operator*` (`const NRMat &rhs`) `const`  
*multiply by given matrix and return the result by value*
- `const NRMat operator*` (`const NRSMat< T > &rhs`) `const`  
*multiply by given symmetric matrix stored in packed form and return the result by value*
- `const NRMat operator&` (`const NRMat &rhs`) `const`  
*direct sum of two matrices*
- `const NRMat operator|` (`const NRMat< T > &rhs`) `const`  
*direct product of two matrices*
- `const NRVec< T > operator*` (`const NRVec< T > &rhs`) `const`  
*multiply by a vector*
- `const NRVec< complex< T > > operator*` (`const NRVec< complex< T > > &rhs`) `const`  
*multiply this matrix of general type T by vector of type complex<T>*
- `const T dot` (`const NRMat &rhs`) `const`  
*inner product of two matrices (taking conjugation into account in the complex case)*
- `const NRMat oplus` (`const NRMat &rhs`) `const`  
*direct sum*
- `const NRMat otimes` (`const NRMat &rhs`, `bool reversecolumns=false`) `const`  
*direct product*
- `void diagsmultl` (`const NRVec< T > &rhs`)  
*multiply by diagonal matrix from left*
- `void diagsmultr` (`const NRVec< T > &rhs`)  
*multiply by diagonal matrix from right*

- const `NRSMat< T > transposedtimes ()` const  
*for this matrix A compute  $A^T \cdot A$*
- const `NRSMat< T > timestransposed ()` const  
*for this matrix A compute  $A \cdot A^T$*
- const `NRVec< T > rsum ()` const  
*sum the rows*
- const `NRVec< T > csum ()` const  
*sum the columns*
- void `orthonormalize (const bool rowcol, const NRSMat< T > *metric=NULL)`  
*orthonormalize this matrix*
- const `NRVec< T > row (const int i, int l=-1)` const  
*get the  $i^{\text{th}}$  row*
- const `NRVec< T > column (const int j, int l=-1)` const  
*get the  $j^{\text{th}}$  column*
- const `T * diagonalof (NRVec< T > &, const bool divide=0, bool cache=false)` const  
*extract the diagonal elements of this matrix and store them into a vector*
- void `diagonalset (const NRVec< T > &)`  
*set diagonal elements*
- void `gemv (const T beta, NRVec< T > &r, const char trans, const T alpha, const NRVec< T > &x)` const  
*perform the **gemv** operation with vector of type T*
- void `gemv (const T beta, NRVec< complex< T > > &r, const char trans, const T alpha, const NRVec< complex< T > > &x)` const  
*perform the **gemv** operation with vector of type `complex<T>`*
- `T * operator[] (const int i)`  
*determine the pointer to the  $i^{\text{th}}$  row*
- const `T * operator[] (const int i)` const  
*determine the const pointer to the  $i^{\text{th}}$  row*
- `T & operator() (const int i, const int j)`  
*get the reference to the element with indices (i,j)*
- const `T & operator() (const int i, const int j)` const  
*get the const reference to the element with indices (i,j)*
- const `T get_ij (const int i, const int j)` const

*get the copy of the element with indices (i,j)*

- `int nrows () const`  
*get the number of rows*
- `int ncols () const`  
*get the number of columns*
- `int size () const`  
*get the number of matrix elements*
- `void get (int fd, bool dimensions=1, bool transposed=false)`  
*unformatted input*
- `void put (int fd, bool dimensions=1, bool transposed=false) const`  
*unformatted output*
- `void fprintf (FILE *f, const char *format, const int modulo) const`  
*formatted output*
- `void fscanf (FILE *f, const char *format)`  
*formatted input*
- `void clear ()`  
*set all matrix elements equal to zero*
- `void resize (int n, int m)`  
*resize the matrix*
- `operator T * ()`  
*get the pointer to the data*
- `operator const T * () const`  
*get the const pointer to the data*
- `NRMat & transposeme (const int n=0)`  
*in case of square matrix, transpose the leading minor of order n*
- `NRMat & conjugateme ()`  
*conjugate a square matrix*
- `const NRMat transpose (bool conj=false) const`  
*transpose this matrix and return the result by value*
- `const NRMat conjugate () const`  
*conjugate this matrix and return the result by value*
- `const NRMat submatrix (const int fromrow, const int torow, const int fromcol, const int tocol) const`  
*extract specified submatrix*

- void `storesubmatrix` (const int fromrow, const int fromcol, const `NRMat` &rhs)  
*store given matrix at given position into the current matrix*
- void `gemm` (const T &beta, const `NRMat` &a, const char transa, const `NRMat` &b, const char transb, const T &alpha)  
*perform the **gemm** operation*
- const `LA_traits< T >::normtype` `norm` (const T scalar=(T) 0) const  
*compute the norm of this matrix*
- void `axpy` (const T alpha, const `NRMat` &x)  
*add up a scalar multiple of given matrix to the current matrix*
- const T `amax` () const  
*maximal element in the absolute value*
- const T `amin` () const  
*minimal element in the absolute value*
- const T `trace` () const  
*determine the sum of the diagonal elements*
- `NRMat` & `swap_rows` ()  
*swap the order of the rows of the current matrix*
- `NRMat` & `swap_cols` ()  
*swap the order of the columns of the current matrix*
- `NRMat` & `swap_rows_cols` ()  
*swap the order of the rows and columns of the current matrix*
- `SparseSMat< T >` `operator*` (const `SparseSMat< T >` &rhs) const  
*multiply by sparse matrix*
- `NRMat` (const `SparseMat< T >` &rhs)  
*explicit constructor converting sparse matrix into `NRMat<T>` object*
- `NRMat` (const `SparseSMat< T >` &rhs)  
*explicit constructor converting sparse symmetric matrix into `NRMat<T>` object*
- `NRMat` & `operator+=` (const `SparseMat< T >` &rhs)  
*add up given sparse matrix*
- `NRMat` & `operator-=` (const `SparseMat< T >` &rhs)  
*subtract given sparse matrix*
- void `gemm` (const T &beta, const `SparseMat< T >` &a, const char transa, const `NRMat` &b, const char transb, const T &alpha)  
*perform the **gemm** operation*

- void **simplify** ()
- bool **issymmetric** () const
- void **strassen** (const T beta, const **NRMat** &a, const char transa, const **NRMat** &b, const char transb, const T alpha)

*Strassen's multiplication (better than  $O(n^3)$ , analogous syntax to.*

- void **s\_cutoff** (const int, const int, const int, const int) const
- template<>  
**NRMat**< double > & **operator=** (const double &a)
- template<>  
**NRMat**< complex< double > > & **operator=** (const complex< double > &a)
- template<>  
**NRMat**< double > & **operator+=** (const double &a)
- template<>  
**NRMat**< complex< double > > & **operator+=** (const complex< double > &a)
- template<>  
**NRMat**< double > & **operator-=** (const double &a)
- template<>  
**NRMat**< complex< double > > & **operator-=** (const complex< double > &a)
- template<>  
const **NRMat**< double > **operator-** () const
- template<>  
const **NRMat**< complex< double > > **operator-** () const
- template<>  
const **NRVec**< double > **csum** () const
- template<>  
const **NRVec**< complex< double > > **csum** () const
- template<>  
const **NRVec**< double > **rsum** () const
- template<>  
const **NRVec**< complex< double > > **rsum** () const
- template<>  
**NRMat** (const **NRMat**< double > &rhs, bool imagpart)
- template<>  
const **NRSMat**< double > **transposedtimes** () const
- template<>  
const **NRSMat**< complex< double > > **transposedtimes** () const
- template<>  
const **NRSMat**< double > **timestransposed** () const
- template<>  
const **NRSMat**< complex< double > > **timestransposed** () const
- template<>  
void **randomize** (const double &x)
- template<>  
void **randomize** (const double &x)
- template<>  
**NRMat**< double > & **operator\*=** (const double &a)
- template<>  
**NRMat**< complex< double > > & **operator\*=** (const complex< double > &a)
- template<>  
**NRMat**< double > & **operator+=** (const **NRMat**< double > &rhs)



- template<>  
NRMat< complex< double > > & operator+= (const NRMat< complex< double > > &rhs)
- template<>  
NRMat< double > & operator-= (const NRMat< double > &rhs)
- template<>  
NRMat< complex< double > > & operator-= (const NRMat< complex< double > > &rhs)
- template<>  
NRMat< double > & operator+= (const NRSMat< double > &rhs)
- template<>  
NRMat< complex< double > > & operator+= (const NRSMat< complex< double > > &rhs)
- template<>  
NRMat< double > & operator-= (const NRSMat< double > &rhs)
- template<>  
NRMat< complex< double > > & operator-= (const NRSMat< complex< double > > &rhs)
- template<>  
const double dot (const NRMat< double > &rhs) const
- template<>  
const complex< double > dot (const NRMat< complex< double > > &rhs) const
- template<>  
const NRMat< double > operator\* (const NRMat< double > &rhs) const
- template<>  
const NRMat< complex< double > > operator\* (const NRMat< complex< double > > &rhs)  
const
- template<>  
void diagsmultl (const NRVec< double > &rhs)
- template<>  
void diagsmultl (const NRVec< complex< double > > &rhs)
- template<>  
void diagsmulttr (const NRVec< double > &rhs)
- template<>  
void diagsmulttr (const NRVec< complex< double > > &rhs)
- template<>  
const NRMat< double > operator\* (const NRSMat< double > &rhs) const
- template<>  
const NRMat< complex< double > > operator\* (const NRSMat< complex< double > > &rhs)  
const
- template<>  
NRMat< double > & conjugateme ()
- template<>  
NRMat< complex< double > > & conjugateme ()
- template<>  
const NRMat< double > transpose (bool conj) const
- template<>  
const NRMat< complex< double > > transpose (bool conj) const
- template<>  
void gemm (const double &beta, const NRMat< double > &a, const char transa, const NRMat< double > &b, const char transb, const double &alpha)
- template<>  
void gemm (const complex< double > &beta, const NRMat< complex< double > > &a, const char transa, const NRMat< complex< double > > &b, const char transb, const complex< double > &alpha)

- `template<>`  
`const double norm (const double scalar) const`
- `template<>`  
`const double norm (const complex< double > scalar) const`
- `template<>`  
`void axpy (const double alpha, const NRMAT< double > &mat)`
- `template<>`  
`void axpy (const complex< double > alpha, const NRMAT< complex< double > > &mat)`
- `template<>`  
`const double * diagonalof (NRVec< double > &r, const bool divide, bool cache) const`
- `template<>`  
`void diagonalset (const NRVec< double > &r)`
- `template<>`  
`void diagonalset (const NRVec< complex< double > > &r)`
- `template<>`  
`void orthonormalize (const bool rowcol, const NRSMAT< double > *metric)`
- `template<>`  
`NRMAT< double > & swap_rows ()`
- `template<>`  
`NRMAT< complex< double > > & swap_rows ()`
- `template<>`  
`NRMAT< double > & swap_cols ()`
- `template<>`  
`NRMAT< complex< double > > & swap_cols ()`
- `template<>`  
`NRMAT< double > & swap_rows_cols ()`
- `template<>`  
`NRMAT< complex< double > > & swap_rows_cols ()`
- `template<>`  
`const double amax () const`
- `template<>`  
`const double amin () const`
- `template<>`  
`const complex< double > amax () const`
- `template<>`  
`const complex< double > amin () const`
- `template<>`  
`void gemm (const complex< double > &beta, const SparseMat< complex< double > > &a, const char transa, const NRMAT< complex< double > > &b, const char transb, const complex< double > &alpha)`
- `template<>`  
`void gemm (const double &beta, const SparseMat< double > &a, const char transa, const NRMAT< double > &b, const char transb, const double &alpha)`
- `template<>`  
`void s_cutoff (const int c, const int c1, const int c2, const int c3) const`
- `template<>`  
`void strassen (const double beta, const NRMAT< double > &a, const char transa, const NRMAT< double > &b, const char transb, const double alpha)`

## Protected Attributes

- `int nn`  
*number of rows*
- `int mm`  
*number of columns*
- `T * v`  
*pointer to the data stored continuously in emmory*
- `int * count`  
*reference counter*

## Friends

- class `NRVec< T >`
- class `NRSMat< T >`

### 3.2.1 Detailed Description

`template<typename T> class LA::NRMat< T >`

`NRMat<T>` class template implementing the matrix interface.

See also:

`NRVec<T>`, `NRSMat<T>`

### 3.2.2 Constructor & Destructor Documentation

**3.2.2.1** `template<typename T > LA::NRMat< T >::~~NRMat ()` [inline]

standard destructor

destructor for general type

See also:

`NRMat<T>::count`

**3.2.2.2** `template<typename T > LA::NRMat< T >::~NRMat (const int n, const int m, const GPUID loc = undefined)` [inline]

Inlined constructor creating matrix of given size and location. Because of performance reasons, no initialization is done.

**Parameters:**

← *n* vector size (count of elements)

← *loc* location of the underlying data (CPU/GPU)

matrix constructor

**Parameters:**

← *n* number of rows of the matrix being created

← *m* number of cols of the matrix being created

← *loc* location for storing the matrix

**See also:**

[count](#), [v](#), [location](#)

**3.2.2.3** `template<typename T> LA::NRMat< T >::NRMat (const T & a, const int n, const int m, const GPUID loc) [inline]`

inlined constructor creating matrix of given size filled with prescribed value and stored at given location

matrix constructor

**Parameters:**

← *a* value of type T intended for matrix initialization

← *n* number of rows of the matrix being created

← *m* number of cols of the matrix being created

**See also:**

[count](#), [v](#)

**3.2.2.4** `template<typename T> LA::NRMat< T >::NRMat (const T & a, const int n, const int m) [inline]`

inlined constructor creating matrix of given size filled with prescribed value

matrix constructor

**Parameters:**

← *a* value of type T intended for matrix initialization

← *n* number of rows of the matrix being created

← *m* number of cols of the matrix being created

**See also:**

[count](#), [v](#)

### 3.2.2.5 `template<typename T> LA::NRMat< T >::NRMat (const T * a, const int n, const int m)` `[inline]`

inlined constructor creating matrix of given size filled with data located at given memory location

matrix constructor

#### Parameters:

- ← *a* pointer to values of type T intended for matrix initialization
- ← *n* number of rows of the matrix being created
- ← *m* number of cols of the matrix being created

#### See also:

[count](#), [v](#)

### 3.2.2.6 `template<typename T> LA::NRMat< T >::NRMat (const NRMat< T > & rhs)` `[inline]`

inlined copy-constructor

copy constructor implementing shallow copy

#### Parameters:

- ← *rhs* reference object to be copied

#### See also:

[count](#), [v](#)

### 3.2.2.7 `template<typename T> LA::NRMat< T >::NRMat (const NRSMat< T > & rhs)` `[inline, explicit]`

explicit constructor converting symmetric matrix stored in packed form into a [NRMat<T>](#) object

create matrix from a [NRSMat](#) object

#### Parameters:

- ← *rhs* [NRSMat](#) input object to be converted

#### See also:

[count](#), [v](#), [vec.h](#), [NRSMat<T>](#)

### 3.2.2.8 `template<typename T> LA::NRMat< T >::NRMat (const NRVec< T > & rhs, const int n, const int m, const int offset = 0)` `[inline, explicit]`

explicit constructor converting vector into a [NRMat<T>](#) object

create matrix from a vector (shallow copy)

**Parameters:**

- ← *rhs* `NRVec` vector containing the data
- ← *n* number of rows of the matrix being created
- ← *m* number of cols of the matrix being created

**See also:**

[count](#), [v](#), [vec.h](#)

< make just shallow copy

< therefore increase the reference counter

### 3.2.2.9 `template<> LA::NRMat< complex< double > >::NRMat (const NRMat< double > & rhs, bool imagpart) [inline]`

icreate complex double-precision matrix from real double-precision matrix *A*

**Parameters:**

- ← *rhs* real double-precision matrix *A*
- ← *imagpart* flag indicating whether the matrix *A* should be considered as a real or imaginary part of the complex matrix being created

## 3.2.3 Member Function Documentation

### 3.2.3.1 `template<> const complex< double > LA::NRMat< complex< double > >::amax () const [inline]`

for this complex matrix *A*, determine the smallest index of the maximum magnitude element, i.e. maximal element in the 1-norm

**Returns:**

$A_{l,m}$  which maximizes  $\{|\Re A_{i,j}| + |\Im A_{i,j}|\}$

### 3.2.3.2 `template<> const double LA::NRMat< double >::amax () const [inline]`

for this real matrix *A*, determine the first element with largest absolute value

**Returns:**

$A_{l,m}$  which maximizes  $|A_{i,j}|$

### 3.2.3.3 `template<> const complex< double > LA::NRMat< complex< double > >::amin () const [inline]`

for this complex matrix *A*, determine the smallest index of the minimum magnitude element, i.e. minimal element in the 1-norm

**Returns:**

$A_{l,m}$  which minimizes  $\{|\Re A_{i,j}| + |\Im A_{i,j}|\}$

**3.2.3.4** `template<> const double LA::NRMat< double >::amin () const` [inline]

for this real matrix  $A$ , determine the first element with smallest absolute value

**Returns:**

$A_{l,m}$  which minimizes  $|A_{i,j}|$

**3.2.3.5** `template<> void LA::NRMat< complex< double > >::axpy (const complex< double > alpha, const NRMat< complex< double > > & mat)` [inline]

perform the **axpy** operation on the current complex matrix  $A$ , i.e.

$$A \leftarrow A + \alpha B$$

for real matrix  $B$

**Parameters:**

$\leftarrow$  *alpha* complex parameter  $\alpha$

$\leftarrow$  *mat* complex matrix  $B$

**3.2.3.6** `template<> void LA::NRMat< double >::axpy (const double alpha, const NRMat< double > & mat)` [inline]

perform the **axpy** operation on the current real matrix  $A$ , i.e.

$$A \leftarrow A + \alpha B$$

for real matrix  $B$

**Parameters:**

$\leftarrow$  *alpha*  $\alpha$  parameter

$\leftarrow$  *mat* real matrix  $B$

**3.2.3.7** `template<> NRMat< complex< double > > & LA::NRMat< complex< double > >::conjugateme ()` [inline]

conjugate this complex matrix  $A$ , i.e. do nothing :-)

**Returns:**

reference to the modified matrix

**3.2.3.8** `template<> NRMat< double > & LA::NRMat< double >::conjugateme ()` [inline]

conjugate this real matrix  $A$ , i.e. do nothing :-)

**Returns:**

reference to the (unmodified) matrix

### 3.2.3.9 `template<typename T > void LA::NRMat< T >::copyonwrite () [inline]`

ensure that the data of this matrix are referenced exactly once  
create own deep copy

**See also:**

[NRMat<T>::count](#), [NRMat<T>::operator|=\(\)](#)

### 3.2.3.10 `template<> const NRVec< complex< double > > LA::NRMat< complex< double > >::csum () const [inline]`

sum up the columns of the current double-precision complex matrix

**Returns:**

summed columns in a form of a vector

### 3.2.3.11 `template<> const NRVec< double > LA::NRMat< double >::csum () const [inline]`

sum up the columns of the current double-precision real matrix

**Returns:**

summed columns in a form of a vector

### 3.2.3.12 `template<typename T > const NRVec< T > LA::NRMat< T >::csum () const [inline]`

sum the columns

sum up the columns of the current matrix of general type T

**Returns:**

summed columns in a form of a vector

### 3.2.3.13 `template<> void LA::NRMat< complex< double > >::diagmultl (const NRVec< complex< double > > & rhs) [inline]`

multiply this complex matrix  $A$  by diagonal complex matrix  $D$  from left because of cuBlas implementation,  $D$  is required to be placed in CPU memory

**Parameters:**

← *rhs* complex vector representing the diagonal of matrix  $D$



**3.2.3.14** `template<> void LA::NRMAT< double >::diagmultl (const NRVec< double > & rhs)`  
`[inline]`

multiply this real matrix  $A$  by diagonal real matrix  $D$  from left because of cuBlas implementation,  $D$  is required to be placed in CPU memory

**Parameters:**

← *rhs* real vector representing the diagonal of matrix  $D$

**3.2.3.15** `template<> void LA::NRMAT< complex< double > >::diagmultl (const NRVec< complex< double > > & rhs)` `[inline]`

multiply this complex matrix  $A$  by diagonal complex matrix  $D$  from left

**Parameters:**

← *rhs* complex vector representing the diagonal of matrix  $D$

**3.2.3.16** `template<> void LA::NRMAT< double >::diagmultl (const NRVec< double > & rhs)`  
`[inline]`

multiply this real matrix  $A$  by diagonal real matrix  $D$  from right because of cuBlas implementation,  $D$  is required to be placed in CPU memory

**Parameters:**

← *rhs* real vector representing the diagonal of matrix  $D$

**3.2.3.17** `template<> const double * LA::NRMAT< double >::diagonalof (NRVec< double > & r,`  
`const bool divide, bool cache) const` `[inline]`

get or divide by the diagonal of real double-precision matrix in case of nonsquare matrix  $A$ , use the diagonal of  $A^T A$

**Parameters:**

↔ *r* vector for storing the diagonal

← *divide* • `false` save the diagonal to vector *r*  
 • `true` divide the vector *r* by the diagonal elements element-wise

← *cache* reserved

**Returns:**

- `divide == true` NULL
- `divide == false` pointer to the first element of *r*

< temporary variable for storing the scaling factor

**3.2.3.18** `template<> void LA::NRMat< complex< double > >::diagonalset (const NRVec< complex< double > > & r) [inline]`

sets the diagonal of complex matrix to a given complex vector

**Parameters:**

← *r* complex vector which is supposed to be assigned to the diagonal

**Returns:**

void

**3.2.3.19** `template<> void LA::NRMat< double >::diagonalset (const NRVec< double > & r) [inline]`

sets the diagonal of real matrix to a given real vector

**Parameters:**

← *r* real vector which is supposed to be assigned to the diagonal

**Returns:**

void

**3.2.3.20** `template<> const complex< double > LA::NRMat< complex< double > >::dot (const NRMat< complex< double > > & rhs) const [inline]`

compute scalar product of this matrix *A* with given complex matrix *B* i.e. determine  $\sum_{i,j} A_{i,j}^* B_{i,j}$

**Parameters:**

← *rhs* matrix *B*

**Returns:**

computed scalar product

**3.2.3.21** `template<> const double LA::NRMat< double >::dot (const NRMat< double > & rhs) const [inline]`

compute scalar product of this matrix *A* with given real matrix *B* i.e. determine  $\sum_{i,j} A_{i,j} B_{i,j}$

**Parameters:**

← *rhs* matrix *B*

**Returns:**

computed scalar product

**3.2.3.22** `template<typename T> void LA::NRMat< T >::fprintf (FILE *file, const char *format, const int modulo) const` [inline]

formatted output

output of a matrix of general type via lawritemat

**3.2.3.23** `template<typename T> void LA::NRMat< T >::fscanf (FILE *f, const char *format)` [inline]

formatted input

input of a matrix of general type via lawritemat

**3.2.3.24** `template<> void LA::NRMat< double >::gemm (const double &beta, const NRMat< double > &a, const char transa, const NRMat< double > &b, const char transb, const double &alpha)` [inline]

perform the gemm operation for this real matrix  $M$ , i.e. compute

$$M \leftarrow \alpha \times op(A) \times op(B) + \beta \times M$$

**Parameters:**

- ← *beta*  $\beta$
- ← *a* real matrix  $A$
- ← *transa* transposition flag of matrix  $A$
- ← *b* real matrix  $B$
- ← *transb* transposition flag of matrix  $B$
- ← *alpha*  $\alpha$

**3.2.3.25** `template<typename T> void LA::NRMat< T >::get (int fd, bool dim = 1, bool transp = false)` [inline]

unformatted input

routine for raw input

**Parameters:**

- ← *fd* file descriptor for input
- ← *dim* number of elements intended for input, for dim=0 perform copyonwrite
- ← *transp* reserved

**See also:**

[NRVec<T>::get\(\), copyonwrite\(\)](#)

**3.2.3.26** `template<typename T> const T LA::NRMat< T >::get_ij (const int i, const int j) const` `[inline]`

get the copy of the element with indices (i,j)

for a given matrix  $A$ , determine the element with indices (i,j)

**Parameters:**

←  $i$  row number

←  $j$  col number

**Returns:**

const reference to  $A_{i,j}$

Reimplemented in [LA::NRMat\\_from1< T >](#).

**3.2.3.27** `template<typename T> GPUID LA::NRMat< T >::getlocation () const` `[inline]`

routines for CUDA related stuff

- `getlocation()` gets the protected data member location
- `moveto(const GPUID)` moves underlying data between CPU/GPU memory

**3.2.3.28** `template<typename T> int LA::NRMat< T >::ncols () const` `[inline]`

get the number of columns

**Returns:**

number of columns

**3.2.3.29** `template<> const double LA::NRMat< complex< double > >::norm (const complex< double > scalar) const` `[inline]`

compute the Frobenius norm of the current complex matrix  $A$ , i.e.

$$\sqrt{\sum_{i=1}^N \sum_{j=1}^M |A_{i,j}|^2}$$

where  $N$  and  $M$  is the number of rows and columns, respectively

**Parameters:**

← *scalar* complex value subtracted from the diagonal elements

**Returns:**

computed norm

**3.2.3.30** `template<> const double LA::NRMat< double >::norm (const double scalar) const`  
`[inline]`

compute the Frobenius norm of the current real matrix  $A$ , i.e.

$$\sqrt{\sum_{i=1}^N \sum_{j=1}^M |A_{i,j}|^2}$$

where  $N$  and  $M$  is the number of rows and columns, respectively

**Parameters:**

← *scalar* real value subtracted from the diagonal elements

**Returns:**

computed norm

**3.2.3.31** `template<typename T > int LA::NRMat< T >::nrows () const` `[inline]`

get the number of rows

**Returns:**

number of rows

**3.2.3.32** `template<typename T > LA::NRMat< T >::operator const T * () const` `[inline]`

get the const pointer to the data

**Returns:**

const pointer of general type T to the underlying data

**3.2.3.33** `template<typename T > LA::NRMat< T >::operator T * ()` `[inline]`

get the pointer to the data

**Returns:**

pointer of general type T to the underlying data structure

**3.2.3.34** `template<typename T > const T & LA::NRMat< T >::operator() (const int i, const int j) const` `[inline]`

get the const reference to the element with indices (i,j)

for a given matrix  $A$ , determine the element with indices (i,j)

**Parameters:**

←  $i$  row number

←  $j$  col number

**Returns:**

const reference to  $A_{i,j}$

Reimplemented in [LA::NRMat\\_from1< T >](#).

### 3.2.3.35 `template<typename T > T & LA::NRMat< T >::operator() (const int i, const int j)` `[inline]`

get the reference to the element with indices (i,j)

for a given matrix  $A$ , determine the element with indices (i,j)

**Parameters:**

←  $i$  row number

←  $j$  col number

**Returns:**

reference to  $A_{i,j}$

**See also:**

[NRMat<T>::count](#)

Reimplemented in [LA::NRMat\\_from1< T >](#).

### 3.2.3.36 `template<> const NRMat< complex< double > > LA::NRMat< complex< double > >::operator* (const NRSMat< complex< double > > & rhs) const` `[inline]`

multiply this complex matrix  $A$  by symmetric complex matrix  $S$   $S$  is stored in packed form, therefore zhpmv routine is used

**Parameters:**

←  $rhs$  complex symmetric matrix  $S$  stored in packed form

**Returns:**

$A \times S$  by value

### 3.2.3.37 `template<> const NRMat< double > LA::NRMat< double >::operator* (const NRSMat< double > & rhs) const` `[inline]`

multiply this real matrix  $A$  by symmetric matrix  $S$   $S$  is stored in packed form, therefore dspmv routine is used

**Parameters:**

← *rhs* real symmetric matrix  $S$  stored in packed form

**Returns:**

$A \times S$  by value

**3.2.3.38** `template<> const NRMAT< complex< double > > LA::NRMAT< complex< double > >::operator* (const NRMAT< complex< double > > & rhs) const [inline]`

compute product of this matrix  $A$  with given complex matrix  $B$

**Parameters:**

← *rhs* matrix  $B$

**Returns:**

computed product by value

**3.2.3.39** `template<> const NRMAT< double > LA::NRMAT< double >::operator* (const NRMAT< double > & rhs) const [inline]`

compute product of this matrix  $A$  with given real matrix  $B$

**Parameters:**

← *rhs* matrix  $B$

**Returns:**

computed product by value

**3.2.3.40** `template<> NRMAT< complex< double > > & LA::NRMAT< complex< double > >::operator*= (const complex< double > & a) [inline]`

scale complex matrix with a complex factor

**Parameters:**

←  $a$  scaling factor

**Returns:**

reference to the modified matrix

**3.2.3.41** `template<> NRMAT< double > & LA::NRMAT< double >::operator*= (const double & a) [inline]`

scale real matrix with a real factor

**Parameters:**

← *a* scaling factor

**Returns:**

reference to the modified matrix

**3.2.3.42** `template<typename T> NRMat< T > & LA::NRMat< T >::operator*=(const T & a)`  
`[inline]`

multiply by a scalar value

scale matrix of type T with a factor

**Parameters:**

← *a* scaling factor

**Returns:**

reference to the modified matrix

**3.2.3.43** `template<typename T> const NRMat< T > LA::NRMat< T >::operator+(const NRSMat< T > & rhs) const`  
`[inline]`

add given symmetric matrix stored in packed form and return the result by value

[NRMat](#) + [NRSmat](#) via operator +=

**Parameters:**

← *rhs* [NRSMat](#) matrix to be subtracted from current matrix

**Returns:**

result of the subtraction

**See also:**

[NRMat<T>::operator+=\(const NRSMat<T> &\)](#)

**3.2.3.44** `template<> NRMat< complex< double > > & LA::NRMat< complex< double > >::operator+=(const NRSMat< complex< double > > & rhs)`  
`[inline]`

add a given sparse complex matrix *A* stored in packed form to the current complex matrix

**Parameters:**

← *rhs* symmetric complex matrix *A* in packed form

**Returns:**

reference to the modified matrix

**See also:**

[NRSMat<T>](#)



**3.2.3.45** `template<> NRMat< double > & LA::NRMat< double >::operator+=(const NRSMat< double > & rhs) [inline]`

add a given sparse real matrix  $A$  stored in packed form to the current real matrix

**Parameters:**

←  $rhs$  symmetric real matrix  $A$  in packed form

**Returns:**

reference to the modified matrix

**See also:**

[NRSMat<T>](#)

**3.2.3.46** `template<> NRMat< complex< double > > & LA::NRMat< complex< double > >::operator+=(const NRMat< complex< double > > & rhs) [inline]`

add a given complex matrix  $A$  to the current complex matrix

**Parameters:**

←  $rhs$  complex matrix  $A$

**Returns:**

reference to the modified matrix

**3.2.3.47** `template<> NRMat< double > & LA::NRMat< double >::operator+=(const NRMat< double > & rhs) [inline]`

add a given real matrix  $A$  to the current real matrix

**Parameters:**

←  $rhs$  matrix  $A$

**Returns:**

reference to the modified matrix

**3.2.3.48** `template<> NRMat< complex< double > > & LA::NRMat< complex< double > >::operator+=(const complex< double > & a) [inline]`

adds a double-precision complex scalar value to the diagonal elements of this double-precision complex matrix

**Parameters:**

←  $a$  double-precision complex scalar value

**Returns:**

reference to the modified matrix

**3.2.3.49** `template<> NRMat< double > & LA::NRMat< double >::operator+= (const double & a) [inline]`

adds a double-precision real scalar value to the diagonal elements of this double-precision real matrix

**Parameters:**

← *a* double-precision real scalar value

**Returns:**

reference to the modified matrix

**3.2.3.50** `template<typename T> NRMat< T > & LA::NRMat< T >::operator+= (const NRSMat< T > & rhs) [inline]`

add symmetric matrix stored in packed form

add a given general sparse matrix *A* stored in packed form to the current general matrix (of type T)

**Parameters:**

← *rhs* symmetric general matrix *A* in packed form

**Returns:**

reference to the modified matrix

**See also:**

[NRSMat<T>](#)

**3.2.3.51** `template<typename T> NRMat< T > & LA::NRMat< T >::operator+= (const NRMat< T > & rhs) [inline]`

add given matrix

add a given general matrix (type T) *A* to the current complex matrix

**Parameters:**

← *rhs* matrix *A* of type T

**Returns:**

reference to the modified matrix

**3.2.3.52** `template<typename T> NRMat< T > & LA::NRMat< T >::operator+= (const T & a) [inline]`

add scalar value to the diagonal elements

add a scalar value of type T to the diagonal elements of this matrix of general type T

**Returns:**

reference to the modified matrix

**3.2.3.53** `template<> const NRMat< complex< double > > LA::NRMat< complex< double > >::operator- () const` [inline]

implements unary minus operator for this double-precision complex matrix

**Returns:**

modified copy of this matrix

**3.2.3.54** `template<> const NRMat< double > LA::NRMat< double >::operator- () const` [inline]

implements unary minus operator for this double-precision real matrix

**Returns:**

modified copy of this matrix

**3.2.3.55** `template<typename T> const NRMat< T > LA::NRMat< T >::operator- (const NRSMat< T > & rhs) const` [inline]

subtract given symmetric matrix stored in packed form and return the result by value

[NRMat](#) - [NRSMat](#) via operator -=

**Parameters:**

← *rhs* [NRSMat](#) matrix to be subtracted from current matrix

**Returns:**

result of the subtraction

**See also:**

[NRMat<T>::operator-=\(const NRSMat<T> &\)](#)

**3.2.3.56** `template<typename T > const NRMat< T > LA::NRMat< T >::operator- () const` [inline]

unary minus

implements unary minus operator for this matrix of general type T

**Returns:**

modified copy of this matrix

**3.2.3.57** `template<> NRMat< complex< double > > & LA::NRMat< complex< double > >::operator-= (const NRSMat< complex< double > > & rhs)` [inline]

subtract a given sparse complex matrix *A* stored in packed form from the current complex matrix

**Parameters:**

← *rhs* symmetric complex matrix *A* in packed form

**Returns:**

reference to the modified matrix

**See also:**

[NRSMat<T>](#)

### 3.2.3.58 `template<> NRMat< double > & LA::NRMat< double >::operator-= (const NRSMat< double > & rhs) [inline]`

subtract a given sparse real matrix *A* stored in packed form from the current real matrix

**Parameters:**

← *rhs* symmetric real matrix *A* in packed form

**Returns:**

reference to the modified matrix

**See also:**

[NRSMat<T>](#)

### 3.2.3.59 `template<> NRMat< complex< double > > & LA::NRMat< complex< double > >::operator-= (const NRMat< complex< double > > & rhs) [inline]`

subtract a given complex matrix *A* from the current complex matrix

**Parameters:**

← *rhs* matrix *A*

**Returns:**

reference to the modified matrix

### 3.2.3.60 `template<> NRMat< double > & LA::NRMat< double >::operator-= (const NRMat< double > & rhs) [inline]`

subtract a given real matrix *A* from the current real matrix

**Parameters:**

← *rhs* matrix *A*

**Returns:**

reference to the modified matrix

**3.2.3.61** `template<> NRMat< complex< double > > & LA::NRMat< complex< double > >::operator-= (const complex< double > & a) [inline]`

subtracts a double-precision complex scalar value from the diagonal elements of this double-precision complex matrix

**Parameters:**

← *a* double-precision complex scalar value

**Returns:**

reference to the modified matrix

**3.2.3.62** `template<> NRMat< double > & LA::NRMat< double >::operator-= (const double & a) [inline]`

subtracts a double-precision real scalar value from the diagonal elements of this double-precision real matrix

**Parameters:**

← *a* double-precision real scalar value

**Returns:**

reference to the modified matrix

**3.2.3.63** `template<typename T> NRMat< T > & LA::NRMat< T >::operator-= (const NRSMat< T > & rhs) [inline]`

subtract symmetric matrix stored in packed form

subtract a given general sparse matrix *A* stored in packed form from the current general matrix (of type T)

**Parameters:**

← *rhs* symmetric general matrix *A* in packed form

**Returns:**

reference to the modified matrix

**See also:**

[NRSMat<T>](#)

**3.2.3.64** `template<typename T> NRMat< T > & LA::NRMat< T >::operator-= (const NRMat< T > & rhs) [inline]`

subtract given matrix

subtract a given general matrix (type T) *A* from the current matrix

**Parameters:**

← *rhs* matrix *A* of type *T*

**Returns:**

reference to the modified matrix

**3.2.3.65** `template<typename T> NRMat< T > & LA::NRMat< T >::operator= (const T & a)`  
`[inline]`

subtract scalar value to the diagonal elements

subtracts a scalar value of type *T* from the diagonal elements of this matrix of general type *T*

**Returns:**

reference to the modified matrix

**3.2.3.66** `template<> NRMat< complex< double > > & LA::NRMat< complex< double > >::operator= (const complex< double > & a)`  
`[inline]`

assigns a double-precision complex scalar value to the diagonal elements of this double-precision complex matrix

**Parameters:**

← *a* double-precision complex scalar value

**Returns:**

reference to the modified matrix

**3.2.3.67** `template<> NRMat< double > & LA::NRMat< double >::operator= (const double & a)`  
`[inline]`

assigns a double-precision real scalar value to the diagonal elements of this double-precision real matrix

**Parameters:**

← *a* double-precision real scalar value

**Returns:**

reference to the modified matrix

**3.2.3.68** `template<typename T> NRMat< T > & LA::NRMat< T >::operator= (const T & a)`  
`[inline]`

assign scalar value to the diagonal elements

assigns a scalar value of general type *T* to the diagonal elements of this matrix of general type *T*

**Parameters:**

← *a* scalar value of type T

**Returns:**

reference to the modified matrix

**3.2.3.69** `template<typename T> NRMat< T > & LA::NRMat< T >::operator= (const NRMat< T > & rhs) [inline]`

assignment operator performing shallow copy

assignment operator for general type between [NRMat](#) and [NRMat](#)

**See also:**

[count](#)

**Returns:**

reference to the newly assigned matrix

**3.2.3.70** `template<typename T> const T * LA::NRMat< T >::operator[] (const int i) const [inline]`

determine the const pointer to the *i*<sup>th</sup> row

**Parameters:**

← *i* row number

**Returns:**

const pointer to the first element in the *i*-th row

**3.2.3.71** `template<typename T> T * LA::NRMat< T >::operator[] (const int i) [inline]`

determine the pointer to the *i*<sup>th</sup> row

**Parameters:**

← *i* row number

**Returns:**

pointer to the first element in the *i*-th row

**3.2.3.72** `template<typename T> NRMat< T > & LA::NRMat< T >::operator^= (const NRMat< T > & rhs) [inline]`

Hadamard element-wise product.

compute Hadamard (component-wise) product with a given matrix *A*

**Parameters:**

← *rhs* matrix *A*

**See also:**

[count](#), [operator\\*](#)

**Returns:**

reference to the multiplied matrix

### 3.2.3.73 `template<typename T > NRMat< T > & LA::NRMat< T >::operator|= (const NRMat< T > & rhs) [inline]`

assignment operator performing deep copy

perform an explicit deep copy of [NRMat](#) object

**See also:**

[count](#)

**Returns:**

reference to the newly copied matrix

### 3.2.3.74 `template<typename T > const NRMat< T > LA::NRMat< T >::oplus (const NRMat< T > & rhs) const [inline]`

direct sum

implements direct sum with a given matrix *B* via [storesubmatrix\(\)](#)

**Parameters:**

← *rhs* input matrix *B*

**Returns:**

result of the computation (new instance of [NRMat<T>](#))

**See also:**

[submatrix\(\)](#)

### 3.2.3.75 `template<> void LA::NRMat< double >::orthonormalize (const bool rowcol, const NRSMat< double > * metric) [inline]`

perform straightforward orthonormalization via modified Gram-Schmidt process

**Parameters:**

← *rowcol* flag regarding the interpretation of the current matrix

- `true` the vectors being orthonormalized are stored as rows



- `false` the vectors being orthonormalized are stored as columns
- ← *metric* pointer to real symmetric matrix stored in packed form which is used in computing the inner products in the process, the standard inner product is taken into account for `metric == NULL`

**Returns:**

void

### 3.2.3.76 `template<typename T> const NRMAT< T > LA::NRMAT< T >::otimes (const NRMAT< T > &rhs, bool reversecolumns = false) const` [inline]

direct product

implements direct product with a given matrix *B*

**Parameters:**

← *rhs* input matrix *B*

**Returns:**

result of the computation (new instance of [NRMAT<T>](#))

### 3.2.3.77 `template<typename T> void LA::NRMAT< T >::put (int fd, bool dim = 1, bool transp = false) const` [inline]

unformatted output

routine for raw output

**Parameters:**

← *fd* file descriptor for output

← *dim* number of elements intended for output

← *transp* reserved

**See also:**

[NRVec<T>::put\(\)](#)

### 3.2.3.78 `template<> void LA::NRMAT< complex< double > >::randomize (const double &x)` [inline]

fill given complex matrix with random numbers real/imaginary components are generated independently

**Parameters:**

← *x* generate random numbers from the interval [0, *x*]

### 3.2.3.79 `template<> void LA::NRMat< double >::randomize (const double & x) [inline]`

fill given real matrix with random numbers

#### Parameters:

← *x* generate random numbers from the interval [0, *x*]

### 3.2.3.80 `template<typename T > void LA::NRMat< T >::resize (int n, int m) [inline]`

resize the matrix

resize given matrix

#### Parameters:

← *n* number of rows

← *m* number of cols

#### See also:

[copy](#), [NRMat<T>::copyonwrite\(\)](#), [NRMat<T>::operator|=\(\)](#)

#### Returns:

reference to the newly copied matrix

### 3.2.3.81 `template<typename T > const NRVec< T > LA::NRMat< T >::row (const int i, int l = -1) const [inline]`

get the *i*<sup>th</sup> row

extract given row of this matrix of general type T

#### Parameters:

← *i* row index starting from zero

← *l* consider this value as the count of columns

#### Returns:

extracted elements as a NRVec<T> object

### 3.2.3.82 `template<> const NRVec< complex< double > > LA::NRMat< complex< double > >::rsum () const [inline]`

sum up the rows of the current double-precision complex matrix

#### Returns:

summed rows in a form of a vector

**3.2.3.83** `template<> const NRVec< double > LA::NRMat< double >::rsum () const` [inline]

sum up the rows of the current double-precision real matrix

**Returns:**

summed rows in a form of a vector

**3.2.3.84** `template<typename T > const NRVec< T > LA::NRMat< T >::rsum () const`  
[inline]

sum the rows

sum up the rows of the current matrix of general type T

**Returns:**

summed rows in a form of a vector

**3.2.3.85** `template<typename T > int LA::NRMat< T >::size () const` [inline]

get the number of matrix elements

**Returns:**

number of elements

**3.2.3.86** `template<typename T > void LA::NRMat< T >::storesubmatrix (const int fromrow,  
const int fromcol, const NRVec< T > & rhs)` [inline]

store given matrix at given position into the current matrix

places given matrix as submatrix at given position

**Parameters:**

← *fromrow* row-coordinate of top left corner

← *fromcol* col-coordinate of top left corner

← *rhs* input matrix

**3.2.3.87** `template<typename T> void LA::NRMat< T >::strassen (const T beta, const NRVec<  
T > & a, const char transa, const NRVec< T > & b, const char transb, const T alpha)`

Strassen's multiplication (better than  $O(n^3)$ ), analogous syntax to.

**See also:**

[NRMat<T>::gemm\(\)](#)

**3.2.3.88** `template<typename T> const NRMat< T> LA::NRMat< T>::submatrix (const int fromrow, const int torow, const int fromcol, const int tocol) const` [inline]

extract specified submatrix

extract block submatrix

**Parameters:**

← *fromrow* starting row

← *torow* final row

← *fromcol* starting column

← *tocol* final column

**Returns:**

extracted block submatrix

**3.2.3.89** `template<> NRMat< complex< double>> & LA::NRMat< complex< double>>::swap_cols ()` [inline]

interchange the order of the columns of the current (complex) matrix

**Returns:**

reference to the modified matrix

**3.2.3.90** `template<> NRMat< double> & LA::NRMat< double>::swap_cols ()` [inline]

interchange the order of the columns of the current (real) matrix

**Returns:**

reference to the modified matrix

**3.2.3.91** `template<typename T> NRMat< T> & LA::NRMat< T>::swap_cols ()` [inline]

swap the order of the columns of the current matrix

interchange the order of the columns of the current general matrix of type T because of the cuBlas implementation, the GPU version requires that `sizeof(T)sizeof(float)==0`

**Returns:**

reference to the modified matrix

**3.2.3.92** `template<> NRMat< complex< double>> & LA::NRMat< complex< double>>::swap_rows ()` [inline]

interchange the order of the rows of the current (complex) matrix

**Returns:**

reference to the modified matrix

**3.2.3.93** `template<> NRMat< double > & LA::NRMat< double >::swap_rows () [inline]`

interchange the order of the rows of the current (real) matrix

**Returns:**

reference to the modified matrix

**3.2.3.94** `template<typename T > NRMat< T > & LA::NRMat< T >::swap_rows () [inline]`

swap the order of the rows of the current matrix

interchange the order of the rows of the current general matrix of type T for GPU computations, the condition `sizeof(T)sizeof(float)` is required

**Returns:**

reference to the modified matrix

**3.2.3.95** `template<> NRMat< complex< double > > & LA::NRMat< complex< double > >::swap_rows_cols () [inline]`

interchange the order of the rows and columns of the current complex matrix  $A$  of type T, i.e. perform the operation

$$A_{i,j} \leftarrow A_{nn-1-i,mm-1-j}$$

where  $0 \leq i \leq nn$  and  $0 \leq j \leq mm$

**Returns:**

reference to the modified matrix

**3.2.3.96** `template<> NRMat< double > & LA::NRMat< double >::swap_rows_cols () [inline]`

interchange the order of the rows and columns of the current real matrix  $A$  of type T, i.e. perform the operation

$$A_{i,j} \leftarrow A_{nn-1-i,mm-1-j}$$

where  $0 \leq i \leq nn$  and  $0 \leq j \leq mm$

**Returns:**

reference to the modified matrix

**3.2.3.97** `template<typename T > NRMat< T > & LA::NRMat< T >::swap_rows_cols () [inline]`

swap the order of the rows and columns of the current matrix

interchange the order of the rows and columns of the current general matrix  $A$  of type T, i.e. perform the operation

$$A_{i,j} \leftarrow A_{nn-1-i,mm-1-j}$$

where  $0 \leq i \leq nn$  and  $0 \leq j \leq mm$

**Returns:**

reference to the modified matrix

**3.2.3.98** `template<> const NRSMat< complex< double > > LA::NRMat< complex< double > >::timestransposed () const [inline]`

for a given complex matrix  $A$  compute  $AA^\dagger$

**Returns:**

complex [NRSMat](#) object because of the hermiticity of  $AA^\dagger$

**3.2.3.99** `template<> const NRSMat< double > LA::NRMat< double >::timestransposed () const [inline]`

for a given real matrix  $A$  compute  $AA^T$

**Returns:**

real [NRSMat](#) object because of the symmetry of  $AA^T$

< resulting matrix has nn rows

**3.2.3.100** `template<typename T > const NRSMat< T > LA::NRMat< T >::timestransposed () const [inline]`

for this matrix  $A$  compute  $A \cdot A^T$

for a given matrix  $A$  (general type) compute  $A^T A$

**Returns:**

[NRSMat<T>](#) object because of the symmetry of the result

**3.2.3.101** `template<typename T > const T LA::NRMat< T >::trace () const [inline]`

determine the sum of the diagonal elements

compute the trace of current general square matrix  $A$ , i.e.

$$\sum_{i=1}^N A_{i,i}$$

where  $N$  is the order of the matrix

**3.2.3.102** `template<> const NRMat< complex< double > > LA::NRMat< complex< double > >::transpose (bool conj) const [inline]`

compute transpose (optionally conjugated) of this real matrix  $A$

**Parameters:**

← *conj* conjugation flag

**Returns:**

transposed (conjugated) matrix by value

**3.2.3.103** `template<> const NRMat< double > LA::NRMat< double >::transpose (bool conj)`  
`const [inline]`

compute transpose (optionally conjugated) of this real matrix  $A$

**Parameters:**

← *conj* conjugation flag, unused for real matrices

**Returns:**

transposed (conjugated) matrix by value

**3.2.3.104** `template<> const NRSMat< complex< double > > LA::NRMat< complex< double >`  
`>::transposedtimes () const [inline]`

for a given complex matrix  $A$  compute  $A^\dagger A$

**Returns:**

complex [NRSMat](#) object because of the hermiticity of  $A^\dagger A$

**3.2.3.105** `template<> const NRSMat< double > LA::NRMat< double >::transposedtimes ()`  
`const [inline]`

for a given real matrix  $A$  compute  $A^T A$

**Returns:**

real [NRSMat](#) object because of the symmetry of  $A^T A$

< resulting matrix has mm rows

**3.2.3.106** `template<typename T > const NRSMat< T > LA::NRMat< T >::transposedtimes ()`  
`const [inline]`

for this matrix  $A$  compute  $A^T \cdot A$

for a given matrix  $A$  (general type) compute  $A^T A$

**Returns:**

[NRSMat<T>](#) object because of the symmetry of the result

**3.2.3.107** `template<typename T> NRMat< T > & LA::NRMat< T >::transposeme (const int _n = 0) [inline]`

in case of square matrix, transpose the leading minor of order *n*

compute matrix transposition for a principal leading minor

**Parameters:**

← *\_n* order of the leading minor

**Returns:**

reference to the modified matrix

< transpose the entire matrix

The documentation for this class was generated from the following files:

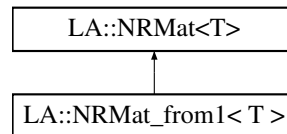
- mat.h
- mat.cc
- sparsemat.cc
- sparsemat.h
- sparsesmat.cc
- sparsesmat.h



### 3.3 LA::NRMat\_from1< T > Class Template Reference

```
#include <mat.h>
```

Inheritance diagram for LA::NRMat\_from1< T >::



#### Public Member Functions

- **NRMat\_from1** (const int n)
- **NRMat\_from1** (const [NRMat](#)< T > &rhs)
- **NRMat\_from1** (const int n, const int m)
  - be able to convert the parent class transparently to this*
- **NRMat\_from1** (const T &a, const int n, const int m)
- **NRMat\_from1** (const T \*a, const int n, const int m)
- const T & **operator()** (const int i, const int j) const
  - get the const reference to the element with indices (i,j)*
- T & **operator()** (const int i, const int j)
  - get the reference to the element with indices (i,j)*
- const T **get\_ij** (const int i, const int j) const
  - get the copy of the element with indices (i,j)*

#### 3.3.1 Detailed Description

```
template<typename T> class LA::NRMat_from1< T >
```

implements [NRMat](#)<T> functionality with indexing from 1 all possible constructors have to be given explicitly, other stuff is inherited with exception of the `operator()` which differs

#### 3.3.2 Member Function Documentation

**3.3.2.1** `template<typename T > const T LA::NRMat_from1< T >::get_ij (const int i, const int j)`  
`const` [inline]

get the copy of the element with indices (i,j)

for a given matrix *A*, determine the element with indices (i,j)

##### Parameters:

← *i* row number

←  $j$  col number

**Returns:**

const reference to  $A_{i,j}$

Reimplemented from [LA::NRMat< T >](#).

**3.3.2.2** `template<typename T > T& LA::NRMat_from1< T >::operator() (const int i, const int j)`  
`[inline]`

get the reference to the element with indices (i,j)

for a given matrix  $A$ , determine the element with indices (i,j)

**Parameters:**

←  $i$  row number

←  $j$  col number

**Returns:**

reference to  $A_{i,j}$

**See also:**

[NRMat<T>::count](#)

Reimplemented from [LA::NRMat< T >](#).

**3.3.2.3** `template<typename T > const T& LA::NRMat_from1< T >::operator() (const int i, const int j) const`  
`[inline]`

get the const reference to the element with indices (i,j)

for a given matrix  $A$ , determine the element with indices (i,j)

**Parameters:**

←  $i$  row number

←  $j$  col number

**Returns:**

const reference to  $A_{i,j}$

Reimplemented from [LA::NRMat< T >](#).

The documentation for this class was generated from the following file:

- mat.h

## 3.4 LA::NRSMat< T > Class Template Reference

```
#include <smat.h>
```

### Public Member Functions

- [~NRSMat](#) ()
- [NRSMat](#) ()  
*default constructor of null-matrix*
- [NRSMat](#) (const int n, const GPUID loc=undefined)  
*default constructor*
- [NRSMat](#) (const T &a, const int n)  
*constructor initializing the matrix being created by given scalar value*
- [NRSMat](#) (const T \*a, const int n)  
*constructor initializing the matrix being created by data located at given memory position*
- [NRSMat](#) (const [NRSMat](#) &rhs)  
*copy constructor*
- [NRSMat](#) (const typename LA\_traits\_complex< T >::NRSMat\_Noncomplex\_type &rhs, bool imag-part=false)  
*constructor converting real matrix to its complex counterpart*
- [NRSMat](#) (const [NRMat](#)< T > &rhs)  
*constructor creating symmetric part of a general matrix*
- [NRSMat](#) (const [NRVec](#)< T > &rhs, const int n)  
*construct symmetric matrix by filling the lower triangle with data stored in a vector*
- [NRSMat](#) & [operator=](#) (const [NRSMat](#) &rhs)  
*assignment operator performing shallow copy*
- [NRSMat](#) & [operator|=](#) (const [NRSMat](#) &rhs)  
*assignment operator performing deep copy*
- void [randomize](#) (const typename LA\_traits< T >::normtype &x)  
*fill the matrix with pseudorandom numbers (uniform distribution)*
- [NRSMat](#) & [operator=](#) (const T &a)  
*assign scalar value to diagonal elements*
- int [getcount](#) () const
- GPUID [getlocation](#) () const
- void [moveto](#) (const GPUID dest)
- const bool [operator!=](#) (const [NRSMat](#) &rhs) const  
*relational operator for testing nonequality*

- const bool `operator==` (const `NRSMat` &rhs) const  
*relational operator for testing equality*
- `NRSMat` & `operator*==` (const T &a)
- `NRSMat` & `operator+==` (const T &a)
- `NRSMat` & `operator-==` (const T &a)
- `NRSMat` & `operator+=` (const `NRSMat` &rhs)
- `NRSMat` & `operator-=` (const `NRSMat` &rhs)
- const `NRSMat` `operator-` () const
- const `NRSMat` `operator*` (const T &a) const
- const `NRSMat` `operator+` (const T &a) const
- const `NRSMat` `operator-` (const T &a) const
- const `NRSMat` `operator+` (const `NRSMat` &rhs) const
- const `NRSMat` `operator-` (const `NRSMat` &rhs) const
- const `NRMat`< T > `operator+` (const `NRMat`< T > &rhs) const
- const `NRMat`< T > `operator-` (const `NRMat`< T > &rhs) const
- const `NRMat`< T > `operator*` (const `NRSMat` &rhs) const
- const `NRMat`< T > `operator*` (const `NRMat`< T > &rhs) const
- const T `dot` (const `NRSMat` &rhs) const
- const T `dot` (const `NRVec`< T > &rhs) const
- const `NRVec`< T > `operator*` (const `NRVec`< T > &rhs) const
- const `NRVec`< complex< T > > `operator*` (const `NRVec`< complex< T > > &rhs) const
- const T \* `diagonalof` (`NRVec`< T > &, const bool divide=0, bool cache=false) const
- void `gemv` (const T beta, `NRVec`< T > &r, const char trans, const T alpha, const `NRVec`< T > &x) const
- void `gemv` (const T beta, `NRVec`< complex< T > > &r, const char trans, const T alpha, const `NRVec`< complex< T > > &x) const
- const T & `operator[]` (const int ij) const
- T & `operator[]` (const int ij)
- const T & `operator()` (const int i, const int j) const
- T & `operator()` (const int i, const int j)
- int `nrows` () const
- int `ncols` () const
- int `size` () const
- bool `transp` (const int i, const int j) const
- const LA\_traits< T >::normtype `norm` (const T scalar=(T) 0) const
- void `axpy` (const T alpha, const `NRSMat` &x)
- const T `amax` () const
- const T `amin` () const
- const T `trace` () const
- void `get` (int fd, bool dimensions=1, bool transp=0)
- void `put` (int fd, bool dimensions=1, bool transp=0) const
- void `copyonwrite` ()
- void `clear` ()
- void `resize` (const int n)
- `operator T *` ()
- `operator const T *` () const
- void `fprintf` (FILE \*f, const char \*format, const int modulo) const
- void `fscanf` (FILE \*f, const char \*format)

- **NRSMat** (const SparseMat< T > &rhs)
- **NRSMat** (const SparseSMat< T > &rhs)
- void **simplify** ()
- bool **issymmetric** () const
- template<>  
const **NRSMat**< double > **operator-** () const
- template<>  
const **NRSMat**< complex< double > > **operator-** () const
- template<>  
void **randomize** (const double &x)
- template<>  
void **randomize** (const double &x)
- template<>  
const **NRMat**< double > **operator\*** (const **NRMat**< double > &rhs) const
- template<>  
const **NRMat**< complex< double > > **operator\*** (const **NRMat**< complex< double > > &rhs) const
- template<>  
const **NRMat**< double > **operator\*** (const **NRSMat**< double > &rhs) const
- template<>  
const **NRMat**< complex< double > > **operator\*** (const **NRSMat**< complex< double > > &rhs) const
- template<>  
const double **dot** (const **NRSMat**< double > &rhs) const
- template<>  
const complex< double > **dot** (const **NRSMat**< complex< double > > &rhs) const
- template<>  
const double **dot** (const **NRVec**< double > &rhs) const
- template<>  
const complex< double > **dot** (const **NRVec**< complex< double > > &rhs) const
- template<>  
const double **norm** (const double scalar) const
- template<>  
const double **norm** (const complex< double > scalar) const
- template<>  
void **axpy** (const double alpha, const **NRSMat**< double > &x)
- template<>  
void **axpy** (const complex< double > alpha, const **NRSMat**< complex< double > > &x)
- template<>  
**NRSMat** (const **NRSMat**< double > &rhs, bool imagpart)
- template<>  
**NRSMat**< double > & **operator\*= **(const double &a)****
- template<>  
**NRSMat**< complex< double > > & **operator\*= **(const complex< double > &a)****
- template<>  
**NRSMat**< double > & **operator+= **(const **NRSMat**< double > &rhs)****
- template<>  
**NRSMat**< complex< double > > & **operator+= **(const **NRSMat**< complex< double > > &rhs)****
- template<>  
**NRSMat**< double > & **operator-= **(const **NRSMat**< double > &rhs)****
- template<>  
**NRSMat**< complex< double > > & **operator-= **(const **NRSMat**< complex< double > > &rhs)****

- `template<>`  
const double [amax](#) () const
- `template<>`  
const double [amin](#) () const
- `template<>`  
const complex< double > [amax](#) () const
- `template<>`  
const complex< double > [amin](#) () const

## Protected Attributes

- `int nn`  
*number of rows/columns of this symmetric matrix*
- `T * v`  
*internal pointer to the underlying data structure*
- `int * count`  
*pointer to the reference counter*

## Friends

- class `NRVec< T >`
- class `NRMat< T >`

### 3.4.1 Detailed Description

`template<class T> class LA::NRSMat< T >`

This class implements a general symmetric or hermitian matrix the elements of which are stored in packed form. Particularly the lower triangular part of a symmetric or hermitian matrix of order  $N$  is interpreted as a vector of length  $N(N + 1)/2$  in row-major storage scheme.

### 3.4.2 Constructor & Destructor Documentation

**3.4.2.1** `template<typename T > LA::NRSMat< T >::~~NRSMat ()` [`inline`]

destructor for general type T

See also:

[NRSMat<T>::count](#), [NRSMat<T>::v](#)

**3.4.2.2** `template<typename T > LA::NRSMat< T >::NRSMat (const int n, const GPUID loc = undefined)` [`inline`, `explicit`]

default constructor

constructor of a symmetric matrix stored in packed form

**Parameters:**

- ← *n* number of rows of the matrix being created
- ← *loc* location for storing the matrix

**See also:**

[count](#), [v](#), [location](#)

### 3.4.2.3 `template<typename T> LA::NRSMat< T >::NRSMat (const T & a, const int n)` `[inline]`

constructor initializing the matrix being created by given scalar value

constructor of a symmetric matrix stored in packed form (default location in used)

**Parameters:**

- ← *a* set all matrix elements equal to this value
- ← *n* number of rows of the matrix being created

**See also:**

[count](#), [v](#), [location](#), [NRSMat<T>::NRSMat\(const int, const GPUID\)](#)

### 3.4.2.4 `template<typename T> LA::NRSMat< T >::NRSMat (const T * a, const int n)` `[inline]`

constructor initializing the matrix being created by data located at given memory position

constructor of a symmetric matrix stored in packed form (default location in used)

**Parameters:**

- ← *a* pointer to data of type T used for matrix initialization
- ← *n* number of rows of the matrix being created

**See also:**

[count](#), [v](#), [location](#), [NRSMat<T>::NRSMat\(const int, const GPUID\)](#), [NRSMat<T>::NRSMat\(const T&, const int\)](#)

### 3.4.2.5 `template<typename T> LA::NRSMat< T >::NRSMat (const NRSMat< T > & rhs)` `[inline]`

copy constructor

copy constructor implementing shallow copy

**Parameters:**

- ← *rhs* reference matrix being copied

**See also:**

[count](#), [v](#), [location](#)

**3.4.2.6** `template<typename T> LA::NRSMat< T >::NRSMat (const NRMat< T > & rhs)`  
`[inline, explicit]`

constructor creating symmetric part of a general matrix

constructor symmetrizing given matrix  $A$  of general type  $T$  yielding  $(A + A^T)/2$

**Parameters:**

← *rhs* matrix  $A$

**3.4.2.7** `template<typename T> LA::NRSMat< T >::NRSMat (const NRVec< T > & rhs, const int n)`  
`[inline, explicit]`

construct symmetric matrix by filling the lower triangle with data stored in a vector

constructor interpreting a vector of  $n(n + 1)/2$  elements as a symmetric matrix stored in packed form having  $n$  rows

**Parameters:**

← *rhs* reference matrix being copied

←  $n$  count of rows of the matrix being created

**3.4.2.8** `template<> LA::NRSMat< complex< double > >::NRSMat (const NRSMat< double > & rhs, bool imagpart)`  
`[inline]`

create hermitian matrix  $H$  from given real double-precision symmetric matrix  $S$

**Parameters:**

← *rhs* real double-precision symmetric matrix  $S$

← *imagpart* flag determining whether  $S$  should correspond to the real or imaginary part of  $H$

### 3.4.3 Member Function Documentation

**3.4.3.1** `template<> const complex< double > LA::NRSMat< complex< double > >::amax () const`  
`[inline]`

for this complex symmetric matrix  $A$ , determine the first element with largest "absolute value"

**Returns:**

$A_{l,m}$  which maximizes  $|\Re A_{i,j}| + |\Im A_{i,j}|$

**3.4.3.2** `template<> const double LA::NRSMat< double >::amax () const`  
`[inline]`

for this real symmetric matrix  $A$ , determine the first element with largest absolute value

**Returns:**

$A_{l,m}$  which maximizes  $|A_{i,j}|$



**3.4.3.3** `template<> const complex< double > LA::NRSMat< complex< double > >::amin () const` [inline]

for this complex symmetric matrix  $A$ , determine the first element with smallest "absolute value"

**Returns:**

$A_{l,m}$  which minimizes  $|\Re A_{i,j}| + |\Im A_{i,j}|$

**3.4.3.4** `template<> const double LA::NRSMat< double >::amin () const` [inline]

for this real symmetric matrix  $A$ , determine the first element with smallest absolute value

**Returns:**

$A_{l,m}$  which minimizes  $|A_{i,j}|$

**3.4.3.5** `template<> void LA::NRSMat< complex< double > >::axpy (const complex< double > alpha, const NRSMat< complex< double > > & x)` [inline]

for this complex double-precision hermitian matrix  $H$  stored in packed form, complex scalar value  $\alpha$  and complex double-precision hermitian matrix  $G$ , compute

$$H \leftarrow \alpha G + H$$

**3.4.3.6** `template<> void LA::NRSMat< double >::axpy (const double alpha, const NRSMat< double > & x)` [inline]

for this real double-precision symmetric matrix  $S$  stored in packed form, real scalar value  $\alpha$  and real double-precision symmetric matrix  $T$ , compute

$$S \leftarrow \alpha T + S$$

**3.4.3.7** `template<typename T > void LA::NRSMat< T >::copyonwrite ()` [inline]

detach this `NRSMat<T>` object and create own physical copy of the data

**See also:**

`NRSMat<T>::operator|=, NRSMat<T>::copyonwrite()`

**3.4.3.8** `template<typename T> const T * LA::NRSMat< T >::diagonalof (NRVec< T > & r, const bool divide = 0, const bool cache = false) const` [inline]

get or divide by the diagonal of real symmetric double-precision matrix

**Parameters:**

- ↔ *r* vector for storing the diagonal
- ← *divide*
  - `false` save the diagonal to vector *r*
  - `true` divide the vector *r* by the diagonal elements element-wise
- ← *cache* reserved

**Returns:**

- `divide == true` NULL
- `divide == false` pointer to the first element of *r*

**3.4.3.9** `template<> const complex< double > LA::NRSMat< complex< double > >::dot (const NRVec< complex< double > > & rhs) const` [inline]

compute inner product of this complex double-precision hermitian matrix *H* of order *n* with given complex double-precision vector  $\vec{v}$  of length  $n(n+1)/2$

**Parameters:**

- ← *rhs* complex double-precision vector  $\vec{v}$

**Returns:**

computed inner product

**3.4.3.10** `template<> const double LA::NRSMat< double >::dot (const NRVec< double > & rhs) const` [inline]

compute inner product of this real double-precision symmetric matrix *S* of order *n* with given real double-precision vector  $\vec{v}$  of length  $n(n+1)/2$

**Parameters:**

- ← *rhs* real double-precision vector  $\vec{v}$

**Returns:**

computed inner product

**3.4.3.11** `template<> const complex< double > LA::NRSMat< complex< double > >::dot (const NRSMat< complex< double > > & rhs) const` [inline]

compute inner product of this complex symmetric matrix *A* with given complex symmetric matrix *B* i.e. determine the value of

$$\sum_{i,j} A_{i,j} B_{i,j}$$

**Parameters:**

- ← *rhs* matrix *B*

**Returns:**

computed inner product

### 3.4.3.12 `template<> const double LA::NRSMat< double >::dot (const NRSMat< double > & rhs) const` [inline]

compute inner product of this real symmetric matrix  $A$  with given real symmetric matrix  $B$  i.e. determine the value of

$$\sum_{i,j} A_{i,j} B_{i,j}$$

#### Parameters:

← *rhs* matrix  $B$

#### Returns:

computed inner product

### 3.4.3.13 `template<typename T > void LA::NRSMat< T >::fprintf (FILE *file, const char * format, const int modulo) const` [inline]

routine for formatted output via lawritemat

#### Parameters:

← *file* pointer to FILE structure representing the output file

← *format* format specification in standard printf-like form

← *modulo*

#### See also:

lawritemat()

### 3.4.3.14 `template<typename T > void LA::NRSMat< T >::fscanf (FILE *f, const char *format)` [inline]

routine for formatted input via fscanf

#### Parameters:

← *f* pointer to FILE structure representing the input file

← *format* format specification in standard printf-like form

### 3.4.3.15 `template<typename T > void LA::NRSMat< T >::get (int fd, bool dim = 1, bool transp = 0)` [inline]

routine for raw input

#### Parameters:

← *fd* file descriptor for input

← *dim* number of elements intended for input

← *transp* reserved

#### See also:

[NRSMat<T>::put\(\)](#), [NRSMat<T>::copyonwrite\(\)](#)

**3.4.3.16** `template<typename T> int LA::NRSMat< T >::ncols () const` [inline]

**Returns:**

number of columns of this symmetric matrix of general type T

**3.4.3.17** `template<> const double LA::NRSMat< complex< double > >::norm (const complex< double > scalar) const` [inline]

compute the Frobenius norm of this complex double-precision hermitian matrix

**Parameters:**

← *scalar* subtract this scalar value from the diagonal elements before the norm computation

**3.4.3.18** `template<> const double LA::NRSMat< double >::norm (const double scalar) const` [inline]

compute the Frobenius norm of this real double-precision symmetric matrix

**Parameters:**

← *scalar* subtract this scalar value from the diagonal elements before the norm computation

**3.4.3.19** `template<typename T> int LA::NRSMat< T >::nrows () const` [inline]

**Returns:**

number of rows of this symmetric matrix of general type T

**3.4.3.20** `template<typename T> LA::NRSMat< T >::operator const T * () const` [inline]

**Returns:**

constant pointer of general type T to the underlying data structure

**3.4.3.21** `template<typename T> LA::NRSMat< T >::operator T * ()` [inline]

**Returns:**

pointer of general type T to the underlying data structure

**3.4.3.22** `template<typename T> T & LA::NRSMat< T >::operator() (const int i, const int j)` [inline]

determine matrix element of this symmetric matrix of general type T

**Parameters:**

← *i* row index running from 0

$\leftarrow j$  column index running from 0

**Returns:**

reference to the corresponding matrix element

**See also:**

[count](#), [SMat\\_index](#), [NRSMat<T>::operator\[\]](#)

### 3.4.3.23 `template<typename T > const T & LA::NRSMat< T >::operator() (const int i, const int j) const` [inline]

determine matrix element of this symmetric matrix of general type T

**Parameters:**

$\leftarrow i$  row index running from 0

$\leftarrow j$  column index running from 0

**Returns:**

constant reference to the corresponding matrix element

**See also:**

[count](#), [SMat\\_index](#), [NRSMat<T>::operator\[\]](#)

### 3.4.3.24 `template<> const NRMat< complex< double > > LA::NRSMat< complex< double > >::operator* (const NRMat< complex< double > > & rhs) const` [inline]

multiply this complex double-precision symmetric matrix  $G$  stored in packed form with complex double-precision symmetric matrix  $H$

**Returns:**

matrix product  $G \times H$  (not necessarily symmetric)

### 3.4.3.25 `template<> const NRMat< double > LA::NRSMat< double >::operator* (const NRSMat< double > & rhs) const` [inline]

multiply this real double-precision symmetric matrix  $S$  stored in packed form with real double-precision symmetric matrix  $T$

**Returns:**

matrix product  $S \times T$  (not necessarily symmetric)

**3.4.3.26** `template<> const NRMat< complex< double > > LA::NRMat< complex< double > >::operator* (const NRMat< complex< double > > & rhs) const [inline]`

multiply this real double-precision symmetric matrix  $S$  stored in packed form with real double-precision dense matrix  $A$

**Parameters:**

← *rhs* real double-precision matrix  $A$

**Returns:**

matrix product  $S \times A$

**3.4.3.27** `template<> const NRMat< double > LA::NRMat< double >::operator* (const NRMat< double > & rhs) const [inline]`

multiply this real double-precision symmetric matrix  $S$  stored in packed form with real double-precision dense matrix  $A$

**Parameters:**

← *rhs* real double-precision matrix  $A$

**Returns:**

matrix product  $S \times A$

**3.4.3.28** `template<> NRMat< complex< double > > & LA::NRMat< complex< double > >::operator*=(const complex< double > & a) [inline]`

multiply this complex symmetric matrix with complex scalar value

**Parameters:**

← *a* complex multiplicative factor

**Returns:**

reference to the modified matrix

**3.4.3.29** `template<> NRMat< double > & LA::NRMat< double >::operator*=(const double & a) [inline]`

multiply this real symmetric matrix with real scalar value

**Parameters:**

← *a* real multiplicative factor

**Returns:**

reference to the modified matrix

### 3.4.3.30 `template<typename T> NRSMat< T > & LA::NRSMat< T >::operator*=(const T & a)` [inline]

multiply this symmetric matrix of general type `T` stored in packed form with scalar value of type `T`

#### Parameters:

← `a` multiplicative factor of type `T`

#### Returns:

reference to the modified matrix

### 3.4.3.31 `template<typename T> const NRMat< T > LA::NRSMat< T >::operator+(const NRMat< T > & rhs)` const [inline]

add up given dense matrix of general type `T` with this symmetric matrix of type `T`

#### Parameters:

← `rhs` dense matrix of type `T` to be added

#### Returns:

reference to the modified matrix

### 3.4.3.32 `template<> NRSMat< complex< double > > & LA::NRSMat< complex< double > >::operator+=(const NRSMat< complex< double > > & rhs)` [inline]

add up this complex symmetric matrix with given symmetric matrix

#### Parameters:

← `rhs` complex symmetric matrix to be added

#### Returns:

reference to the modified matrix

### 3.4.3.33 `template<> NRSMat< double > & LA::NRSMat< double >::operator+=(const NRSMat< double > & rhs)` [inline]

add up this real symmetric matrix with given symmetric matrix

#### Parameters:

← `rhs` real symmetric matrix to be added

#### Returns:

reference to the modified matrix

**3.4.3.34** `template<typename T> NRSMat< T > & LA::NRSMat< T >::operator+= (const NRSMat< T > & rhs) [inline]`

add up this symmetric matrix of general type T with given symmetric matrix

**Parameters:**

← *rhs* complex matrix of general type T to be added

**Returns:**

reference to the modified matrix

**3.4.3.35** `template<typename T> NRSMat< T > & LA::NRSMat< T >::operator+= (const T & a) [inline]`

add a scalar value  $\alpha$  of general type T to the diagonal elements of this symmetric matrix of type T

**Parameters:**

← *a* scalar value  $\alpha$

**Returns:**

reference to the modified matrix

**3.4.3.36** `template<> const NRSMat< complex< double > > LA::NRSMat< complex< double > >::operator- () const [inline]`

implements unary minus operator for this hermitian matrix

**Returns:**

modified copy of this matrix

**3.4.3.37** `template<> const NRSMat< double > LA::NRSMat< double >::operator- () const [inline]`

implements unary minus operator for this real symmetric matrix

**Returns:**

modified copy of this matrix

**3.4.3.38** `template<typename T> const NRMat< T > LA::NRSMat< T >::operator- (const NRMat< T > & rhs) const [inline]`

subtracts given dense matrix of general type T from this symmetric matrix of type T

**Parameters:**

← *rhs* dense matrix of type T to be added

**Returns:**

reference to the modified matrix



**3.4.3.39** `template<typename T> const NRSMat< T > LA::NRSMat< T >::operator- () const`  
`[inline]`

implements unary minus operator for this symmetric matrix of general type T

**Returns:**

modified copy of this matrix

**3.4.3.40** `template<> NRSMat< complex< double >> & LA::NRSMat< complex< double >>`  
`::operator-= (const NRSMat< complex< double >> & rhs) [inline]`

subtracts given complex symmetric matrix from this complex symmetric matrix

**Parameters:**

← *rhs* complex symmetric matrix to be subtracted

**Returns:**

reference to the modified matrix

**3.4.3.41** `template<> NRSMat< double > & LA::NRSMat< double >::operator-= (const`  
`NRSMat< double > & rhs) [inline]`

subtracts given real symmetric matrix from this real symmetric matrix

**Parameters:**

← *rhs* real symmetric matrix to be subtracted

**Returns:**

reference to the modified matrix

**3.4.3.42** `template<typename T> NRSMat< T > & LA::NRSMat< T >::operator-= (const`  
`NRSMat< T > & rhs) [inline]`

subtracts given symmetric matrix of general type T from this symmetric matrix of type T

**Parameters:**

← *rhs* symmetric matrix of general type T to be subtracted

**Returns:**

reference to the modified matrix

### 3.4.3.43 `template<typename T> NRSMat< T > & LA::NRSMat< T >::operator-= (const T & a)` `[inline]`

subtract a scalar value  $\alpha$  of general type  $T$  from the diagonal elements of this symmetric matrix of type  $T$

#### Parameters:

$\leftarrow a$  scalar value  $\alpha$

#### Returns:

reference to the modified matrix

### 3.4.3.44 `template<typename T> NRSMat< T > & LA::NRSMat< T >::operator= (const T & a)` `[inline]`

assign scalar value to diagonal elements

zero out this symmetric matrix of general type  $T$  and then set the diagonal elements to prescribed value

#### Parameters:

$\leftarrow a$  scalar value to be assigned to the diagonal

#### Returns:

reference to the modified matrix

### 3.4.3.45 `template<typename T > NRSMat< T > & LA::NRSMat< T >::operator= (const NRSMat< T > & rhs)` `[inline]`

assignment operator performing shallow copy

assignment operator implementing shallow copy of reference [NRSMat<T>](#) object

#### See also:

[NRSMat<T>::operator|=](#), [NRSMat<T>::copyonwrite\(\)](#)

### 3.4.3.46 `template<typename T > T & LA::NRSMat< T >::operator[] (const int ij)` `[inline]`

determine matrix element of this symmetric matrix of general type  $T$  using cumulative index increasing in a row-major way and corresponding to the lower triangular part of the respective dense matrix

#### Parameters:

$\leftarrow ij$  index of the requested element

#### Returns:

reference to the corresponding matrix element

**3.4.3.47** `template<typename T > const T & LA::NRSMat< T >::operator[] (const int ij) const`  
`[inline]`

determine matrix element of this symmetric matrix of general type `T` using cumulative index increasing in a row-major way and corresponding to the lower triangular part of the respective dense matrix, i.e.  $A_{i,j}$  for  $N > i \geq j \geq 0$  corresponds to cumulative index  $i(i+1)/2 + j$

**Parameters:**

← *ij* index of the requested element

**Returns:**

constant reference to the corresponding matrix element

**3.4.3.48** `template<typename T > NRSMat< T > & LA::NRSMat< T >::operator|= (const`  
`NRSMat< T > & rhs) [inline]`

assignment operator performing deep copy

assignment operator implementing deep copy of the reference `NRSMat<T>` object

**See also:**

[NRSMat<T>::operator=](#), [NRSMat<T>::copyonwrite\(\)](#)

**3.4.3.49** `template<typename T > void LA::NRSMat< T >::put (int fd, bool dim = 1, bool transp`  
`= 0) const [inline]`

routine for raw output

**Parameters:**

← *fd* file descriptor for output

← *dim* number of elements intended for output

← *transp* reserved

**See also:**

[NRMat<T>::get\(\)](#), [NRSMat<T>::copyonwrite\(\)](#)

**3.4.3.50** `template<> void LA::NRSMat< complex< double > >::randomize (const double & x)`  
`[inline]`

Fill this hermitian matrix with pseudorandom numbers generated from uniform distribution. The real and imaginary parts are generated independently.

**3.4.3.51** `template<> void LA::NRSMat< double >::randomize (const double & x) [inline]`

fill this real symmetric matrix with pseudorandom numbers generated from uniform distribution

**3.4.3.52** `template<typename T > void LA::NRSMat< T >::resize (const int n) [inline]`

resize this symmetric matrix of general type T

**Parameters:**

← *n* requested number of rows (columns)

**3.4.3.53** `template<typename T > int LA::NRSMat< T >::size () const [inline]`

**Returns:**

number of elements of this symmetric matrix of general type T

**3.4.3.54** `template<typename T > const T LA::NRSMat< T >::trace () const [inline]`

**Returns:**

the sum of the diagonal elements

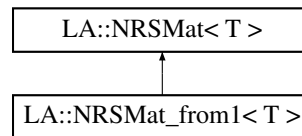
The documentation for this class was generated from the following files:

- smat.h
- smat.cc
- sparsemat.cc
- sparsesmat.h

## 3.5 LA::NRSMat\_from1< T > Class Template Reference

```
#include <smat.h>
```

Inheritance diagram for LA::NRSMat\_from1< T >::



### Public Member Functions

- **NRSMat\_from1** (const int n)
- **NRSMat\_from1** (const [NRSMat](#)< T > &rhs)
- **NRSMat\_from1** (const T &a, const int n)
- **NRSMat\_from1** (const T \*a, const int n)
- **NRSMat\_from1** (const [NRMat](#)< T > &rhs)
- **NRSMat\_from1** (const [NRVec](#)< T > &rhs, const int n)
- const T & **operator()** (const int i, const int j) const
- T & **operator()** (const int i, const int j)

### 3.5.1 Detailed Description

**template<typename T> class LA::NRSMat\_from1< T >**

generate operators relating [NRSMat](#)<T> objects and scalars corresponding macro is defined in [vec.h](#) generate operators relating in general two [NRSMat](#)<T> objects corresponding macro is defined in [vec.h](#) class implementing [NRSMat](#)<T> functionality with indices running from 1 almost all function members are inherited, only constructors are given explicitly

The documentation for this class was generated from the following file:

- smat.h

### 3.6 LA::NRVec< T > Class Template Reference

NRVec<T> class template implementing the vector interface.

```
#include <vec.h>
```

#### Public Types

- typedef T **ROWTYPE**

#### Public Member Functions

- [~NRVec](#) ()  
*standard destructor*
- [NRVec](#) ()
- [NRVec](#) (const int n, const GPUID loc=undefined)
- [NRVec](#) (const T &a, const int n)  
*inlined constructor creating vector of given size filled with prescribed value*
- [NRVec](#) (const T \*a, const int n)  
*inlined constructor creating vector of given size filled with data located at given memory location*
- [NRVec](#) (T \*a, const int n, bool skeleton)  
*inlined constructor creating vector of given size filled with data located at given memory location*
- [NRVec](#) (const [NRVec](#) &rhs)  
*inlined copy constructor*
- [NRVec](#) (const typename LA\_traits\_complex< T >::NRVec\_Noncomplex\_type &rhs, bool imag-part=false)  
*complexifying constructor*
- [NRVec](#) (const [NRSMat](#)< T > &S)  
*explicit inlined constructor converting symmetric matrix into a vector*
- [NRVec](#) (const [NRMat](#)< T > &rhs)
- GPUID [getlocation](#) () const
- void **moveto** (const GPUID dest)
- void [copyonwrite](#) ()  
*create separate copy of the data corresponding to this vector*
- void [clear](#) ()  
*purge this vector*
- [NRVec](#) & [operator=](#) (const [NRVec](#) &rhs)  
*assignment operator assigns given vector*
- [NRVec](#) & [operator=](#) (const T &a)

*assignment operator assigns given scalar to each element of this vector*

- void **randomize** (const typename LA\_traits< T >::normtype &x)  
*fills in this vector with pseudo-random numbers generated using uniform distribution*
- NVec & **operator|=** (const NVec &rhs)  
*perform deep-copy of given vector*
- const bool **operator!=** (const NVec &rhs) const  
*relational operators*
- const bool **operator==** (const NVec &rhs) const
- const bool **operator>** (const NVec &rhs) const
- const bool **operator<** (const NVec &rhs) const
- const bool **operator>=** (const NVec &rhs) const
- const bool **operator<=** (const NVec &rhs) const
- const NVec **operator-** () const  
*unary minus*
- NVec & **operator+=** (const NVec &rhs)  
*bunch of vector-vector arithmetic operators defined element-wise*
- NVec & **operator-=** (const NVec &rhs)
- NVec & **operator\*=** (const NVec &rhs)
- NVec & **operator/=** (const NVec &rhs)
- const NVec **operator+** (const NVec &rhs) const
- const NVec **operator-** (const NVec &rhs) const
- NVec & **operator+=** (const T &a)  
*bunch of scalar-vector arithmetic operators defined element-wise*
- NVec & **operator-=** (const T &a)
- NVec & **operator\*=** (const T &a)
- const NVec **operator+** (const T &a) const
- const NVec **operator-** (const T &a) const
- const NVec **operator\*** (const T &a) const
- int **getcount** () const  
*determine the actual value of the reference counter*
- const T **operator\*** (const NVec &rhs) const  
*compute the Euclidean inner product (with conjugation in complex case)*
- const T **dot** (const NVec &rhs) const
- const T **dot** (const T \*a, const int stride=1) const  
*compute the Euclidean inner product (with conjugation in complex case) with a stride-vector*
- void **gemv** (const T beta, const NRMAT< T > &a, const char trans, const T alpha, const NVec &x)
- void **gemv** (const T beta, const NRSMAT< T > &a, const char trans, const T alpha, const NVec &x)
- void **gemv** (const T beta, const SparseMat< T > &a, const char trans, const T alpha, const NVec &x, const bool treat\_as\_symmetric=false)

- void **gemv** (const typename LA\_traits\_complex< T >::Component\_type beta, const typename LA\_traits\_complex< T >::NRMat\_Noncomplex\_type &a, const char trans, const typename LA\_traits\_complex< T >::Component\_type alpha, const **NRVec** &x)
- void **gemv** (const typename LA\_traits\_complex< T >::Component\_type beta, const typename LA\_traits\_complex< T >::NRSMat\_Noncomplex\_type &a, const char trans, const typename LA\_traits\_complex< T >::Component\_type alpha, const **NRVec** &x)
- const **NRVec operator\*** (const **NRMat**< T > &mat) const  
*multiply given matrix with this vector from left*
- const **NRVec operator\*** (const **NRSMat**< T > &mat) const  
*multiply given symmetric matrix in packed form with this vector from left*
- const **NRVec operator\*** (const **SparseMat**< T > &mat) const  
*multiply given sparse matrix with this vector from left*
- const **NRMat**< T > **otimes** (const **NRVec**< T > &rhs, const bool conjugate=false, const T &scale=1) const  
*compute the outer product of two vectors*
- const **NRMat**< T > **operator|** (const **NRVec**< T > &rhs) const  
*operator for outer product computation*
- const T **sum** () const  
*compute the sum of the vector elements*
- const LA\_traits< T >::normtype **asum** () const  
*compute the sum of the absolute values of the elements of this vector*
- T & **operator[ ]** (const int i)  
*indexing operator - index running from zero*
- const T & **operator[ ]** (const int i) const
- void **setcoldim** (int i)  
*dummy routine*
- **operator T \*** ()  
*get the pointer to the underlying data structure*
- **operator const T \*** () const  
*get the constant pointer to the underlying data structure*
- void **axpy** (const T alpha, const **NRVec** &x)  
*add up a scalar multiple of a given vector*
- void **axpy** (const T alpha, const T \*x, const int stride=1)  
*add up a scalar multiple of a given vector with given stride*
- int **size** () const  
*determine the number of elements*



- void `resize` (const int n)  
*resize the current vector*
- const LA\_traits< T >::normtype `norm` () const  
*determine the norm of this vector*
- `NRVec` & `normalize` (typename LA\_traits< T >::normtype \*norm=0)  
*normalize this vector and optionally save the norm*
- const `NRVec` `unitvector` () const  
*get normalized copy of this vector*
- const T `amax` () const  
*determine the maximal element (in the absolute value) of this vector*
- const T `amin` () const  
*determine the minimal element (in the absolute value) of this vector*
- void `fprintf` (FILE \*f, const char \*format, const int modulo) const  
*routine for formatted output*
- void `put` (int fd, bool dimensions=1, bool transp=0) const  
*routine for unformatted output*
- void `fscanf` (FILE \*f, const char \*format)  
*routine for formatted input*
- void `get` (int fd, bool dimensions=1, bool transp=0)  
*routine for unformatted input*
- `NRVec` (const SparseMat< T > &rhs)  
*constructor creating vector from sparse matrix*
- void `simplify` ()  
*routine for compatibility with sparse types*
- bool `bigger` (int i, int j) const  
*determine whether the  $i^{\text{th}}$  element is bigger than the  $j^{\text{th}}$  element*
- bool `smaller` (int i, int j) const  
*determine whether the  $i^{\text{th}}$  element is bigger than the  $j^{\text{th}}$  element*
- void `swap` (int i, int j)  
*swap the  $i^{\text{th}}$  and  $j^{\text{th}}$  element*
- int `sort` (int direction=0, int from=0, int to=-1, int \*perm=NULL)  
*sort by default in ascending order and return the parity of corresponding permutation resulting to this order*
- `NRVec` & `call_on_me` (T(\*\_F)(const T &))

*apply given function to each element*

- `template<>`  
`const NRVec< double > operator- () const`
- `template<>`  
`const NRVec< complex< double > > operator- () const`
- `template<>`  
`void randomize (const double &x)`
- `template<>`  
`void randomize (const double &x)`
- `template<>`  
`NRVec (const NRVec< double > &rhs, bool imagpart)`
- `template<>`  
`void axpy (const double alpha, const NRVec< double > &x)`
- `template<>`  
`void axpy (const complex< double > alpha, const NRVec< complex< double > > &x)`
- `template<>`  
`void axpy (const double alpha, const double *x, const int stride)`
- `template<>`  
`void axpy (const complex< double > alpha, const complex< double > *x, const int stride)`
- `template<>`  
`NRVec< double > & operator= (const double &a)`
- `template<>`  
`NRVec< complex< double > > & operator= (const complex< double > &a)`
- `template<>`  
`NRVec< double > & normalize (double *norm)`
- `template<>`  
`NRVec< complex< double > > & normalize (double *norm)`
- `template<>`  
`void gemv (const double beta, const NRMat< double > &A, const char trans, const double alpha, const NRVec &x)`
- `template<>`  
`void gemv (const double beta, const NRMat< double > &A, const char trans, const double alpha, const NRVec< complex< double > > &x)`
- `template<>`  
`void gemv (const complex< double > beta, const NRMat< complex< double > > &A, const char trans, const complex< double > alpha, const NRVec< complex< double > > &x)`
- `template<>`  
`void gemv (const double beta, const NRSMat< double > &A, const char trans, const double alpha, const NRVec &x)`
- `template<>`  
`void gemv (const double beta, const NRSMat< double > &A, const char trans, const double alpha, const NRVec< complex< double > > &x)`
- `template<>`  
`void gemv (const complex< double > beta, const NRSMat< complex< double > > &A, const char trans, const complex< double > alpha, const NRVec< complex< double > > &x)`
- `template<>`  
`const NRMat< double > otimes (const NRVec< double > &b, const bool conj, const double &scale) const`
- `template<>`  
`const NRMat< complex< double > > otimes (const NRVec< complex< double > > &b, const bool conj, const complex< double > &scale) const`

- template<>  
NRVec< double > & operator+= (const double &a)
- template<>  
NRVec< complex< double > > & operator+= (const complex< double > &a)
- template<>  
NRVec< double > & operator-= (const double &a)
- template<>  
NRVec< complex< double > > & operator-= (const complex< double > &a)
- template<>  
NRVec< double > & operator+= (const NRVec< double > &rhs)
- template<>  
NRVec< complex< double > > & operator+= (const NRVec< complex< double > > &rhs)
- template<>  
NRVec< double > & operator-= (const NRVec< double > &rhs)
- template<>  
NRVec< complex< double > > & operator-= (const NRVec< complex< double > > &rhs)
- template<>  
NRVec< double > & operator\*=(const double &a)
- template<>  
NRVec< complex< double > > & operator\*=(const complex< double > &a)
- template<>  
const double operator\*(const NRVec< double > &rhs) const
- template<>  
const complex< double > operator\*(const NRVec< complex< double > > &rhs) const
- template<>  
const double dot (const double \*y, const int stride) const
- template<>  
const complex< double > dot (const complex< double > \*y, const int stride) const
- template<>  
const double asum () const
- template<>  
const double asum () const
- template<>  
const double norm () const
- template<>  
const double norm () const
- template<>  
const double amax () const
- template<>  
const double amin () const
- template<>  
const complex< double > amax () const
- template<>  
const complex< double > amin () const

## Protected Attributes

- int nn  
*size of the vector*
- T \* v

*pointer to the underlying data structure*

- `int * count`

*pointer to the reference-counter*

## Friends

- class `NRSMat< T >`
- class `NRMAT< T >`
- template<typename U >  
`NRVec< complex< U > > complexify (const NRVec< U > &)`

## 3.6.1 Detailed Description

`template<typename T> class LA::NRVec< T >`

`NRVec<T>` class template implementing the vector interface.

See also:

[NRMAT<T>](#), [NRSMat<T>](#)

## 3.6.2 Constructor & Destructor Documentation

**3.6.2.1** `template<typename T > LA::NRVec< T >::~~NRVec ()` [inline]

standard destructor

generate operators involving vector and scalar generate operators involving vector and vector destructor for general vector decreases the reference count and performs deallocation if necessary

**3.6.2.2** `template<typename T> LA::NRVec< T >::~NRVec ()` [inline]

inlined constructor creating zero vector of general type T

**3.6.2.3** `template<typename T> LA::NRVec< T >::~NRVec (const int n, const GPUID loc = undefined)` [inline, explicit]

Explicit inlined constructor creating vector of given size and location. Because of performance reasons, no initialization is done.

**Parameters:**

← *n* vector size (count of elements)

← *loc* location of the underlying data (CPU/GPU)

**3.6.2.4** `template<typename T> LA::NRVec< T >::NRVec (const T & a, const int n) [inline]`

inlined constructor creating vector of given size filled with prescribed value

inline constructor creating vector of given size filled with prescribed value

**Parameters:**

- ← *a* value to be assigned to all vector elements
- ← *n* required vector size

**3.6.2.5** `template<typename T> LA::NRVec< T >::NRVec (const T * a, const int n) [inline]`

inlined constructor creating vector of given size filled with data located at given memory location

inline constructor creating vector of given size filled with given data

**Parameters:**

- ← *a* pointer to the data
- ← *n* required vector size

**3.6.2.6** `template<typename T> LA::NRVec< T >::NRVec (T * a, const int n, bool skeleton) [inline]`

inlined constructor creating vector of given size filled with data located at given memory location

inline constructor creating vector of given size filled with given data

**Parameters:**

- ← *a* pointer to the data
- ← *n* required vector size
- ← *skeleton* if equal to true, only the internal data pointer is modified and reference counter is set to two, i.e. no data deallocation occurs in destructor

**3.6.2.7** `template<typename T> LA::NRVec< T >::NRVec (const NRVec< T > & rhs) [inline]`

inlined copy constructor

inline copy constructor

**Parameters:**

- ← *rhs* reference vector being copied

**3.6.2.8** `template<typename T> LA::NRVec< T >::NRVec (const NRSMat< T > & rhs) [inline, explicit]`

explicit inlined constructor converting symmetric matrix into a vector

inline constructor interpreting symmetric matrix of order *n* stored in packed form as a linear vector consisting of  $n(n + 1)/2$  elements

**Parameters:**

← *rhs* symmetric matrix of type `NRSMat<T>`

**See also:**

`NRSMat<T>`

using macro NN2 defined in `smat.h`

### 3.6.2.9 `template<typename T> LA::NVec< T >::NVec (const NRMat< T > & rhs)` `[inline, explicit]`

conversion constructor interpreting a given matrix with  $N$  rows and  $M$  columns of general type  $T$  as a vector of  $N \times M$  elements

**Parameters:**

← *rhs* matrix being converted

**See also:**

`NRMat<T>::NRMat()`

### 3.6.2.10 `template<> LA::NVec< complex< double > >::NVec (const NVec< double > & rhs, bool imagpart)` `[inline]`

constructor creating complex vector from a real one

**Parameters:**

← *rhs* the real vector being converted into the complex one

← *imagpart* • `true` vector *rhs* is interpreted as the imaginary part of the new complex vector  
 • `false` vector *rhs* is interpreted as the real part of the new complex vector

**Returns:**

- `false` current vector is bigger than vector *rhs*
- `true` current vector is smaller than vector *rhs*

## 3.6.3 Member Function Documentation

### 3.6.3.1 `template<> const complex< double > LA::NVec< complex< double > >::amax () const` `[inline]`

for a given complex vector  $\vec{v}$ , determine the smallest index of the maximum magnitude element, i.e. maximal element in the 1-norm

**Returns:**

$\vec{v}_j$  which maximizes  $\{|\Re\vec{v}_i| + |\Im\vec{v}_i|\}$

**3.6.3.2** `template<> const double LA::NVec< double >::amax () const` [inline]

for this real vector  $\vec{x}$  determine the element with largest absolute value

**Returns:**

$$\vec{x}_i \text{ where } |x_i| = \max_j |x_j|$$

**3.6.3.3** `template<> const complex< double > LA::NVec< complex< double > >::amin () const` [inline]

for a given complex vector  $\vec{v}$ , determine the smallest index of the minimum magnitude element, i.e. minimal element in the 1-norm

**Returns:**

$$\vec{v}_j \text{ which minimizes } \{|\Re \vec{v}_i| + |\Im \vec{v}_i|\}$$

**3.6.3.4** `template<> const double LA::NVec< double >::amin () const` [inline]

for this real vector  $\vec{x}$  determine the element with smallest absolute value

**Returns:**

$$\vec{x}_i \text{ where } |x_i| = \min_j |x_j|$$

**3.6.3.5** `template<> const double LA::NVec< complex< double > >::asum () const` [inline]

for this complex vector  $\vec{x}$  compute the expression

$$\sum_{i=1}^N |\Re \vec{x}_i| + |\Im \vec{x}_i|$$

**Returns:**

the value of this sum

**3.6.3.6** `template<> const double LA::NVec< double >::asum () const` [inline]

computes the sum of the absolute values of the elements of this real vector  $\vec{x}$

**Returns:**

$$\sum_{i=1}^N |x_i|$$

**3.6.3.7** `template<> void LA::NRVec< complex< double > >::axpy (const complex< double > alpha, const complex< double > * x, const int stride) [inline]`

perform the **axpy** operation on the current complex vector  $\vec{v}$ , i.e.

$$\vec{v} \leftarrow \vec{v} + \alpha \vec{x}$$

**Parameters:**

- ← *alpha* double-precision complex parameter  $\alpha$
- ← *x* pointer to double-precision complex data
- ← *stride* sets the stride

**3.6.3.8** `template<> void LA::NRVec< double >::axpy (const double alpha, const double * x, const int stride) [inline]`

perform the **axpy** operation on the current real vector  $\vec{v}$ , i.e.

$$\vec{v} \leftarrow \vec{v} + \alpha \vec{x}$$

**Parameters:**

- ← *alpha*  $\alpha$  parameter
- ← *x* pointer to double-precision real data
- ← *stride* sets the stride

**3.6.3.9** `template<> void LA::NRVec< complex< double > >::axpy (const complex< double > alpha, const NRVec< complex< double > > & x) [inline]`

perform the **axpy** operation on the current complex vector  $\vec{v}$ , i.e.

$$\vec{v} \leftarrow \vec{v} + \alpha \vec{x}$$

**Parameters:**

- ← *alpha*  $\alpha$  parameter
- ← *x* complex vector  $\vec{x}$

**3.6.3.10** `template<> void LA::NRVec< double >::axpy (const double alpha, const NRVec< double > & x) [inline]`

perform the **axpy** operation on the current real vector  $\vec{v}$ , i.e.

$$\vec{v} \leftarrow \vec{v} + \alpha \vec{x}$$

**Parameters:**

- ← *alpha* double-precision real parameter  $\alpha$
- ← *x* double-precision real vector  $\vec{x}$



**3.6.3.11** `template<typename T> void LA::NRVec< T >::copyonwrite ()` [inline]

create separate copy of the data corresponding to this vector

make own copy of the underlying data connected with this vector

**3.6.3.12** `template<> const complex< double > LA::NRVec< complex< double > >::dot (const complex< double > * y, const int stride) const` [inline]

computes the inner product of this complex vector  $\vec{x}$  with given complex data

**Parameters:**

← *y* pointer to the double-precision complex array (sufficient length assumed)

← *stride* specifies the stride regarding the data points to by *y*

**Returns:**

$$\sum_{i=1}^N \vec{x}_i \cdot y_{\text{stride} \cdot (i-1) + 1}$$

**3.6.3.13** `template<> const double LA::NRVec< double >::dot (const double * y, const int stride) const` [inline]

computes the inner product of this real vector  $\vec{x}$  with given real data

**Parameters:**

← *y* pointer to the double-precision real array (sufficient length assumed)

← *stride* specifies the stride regarding the data points to by *y*

**Returns:**

$$\sum_{i=1}^N \vec{x}_i \cdot y_{\text{stride} \cdot (i-1) + 1}$$

**3.6.3.14** `template<typename T> void LA::NRVec< T >::fprintf (FILE * file, const char * format, const int modulo) const` [inline]

routine for formatted output

routine for formatted output via lawritemat

**Parameters:**

← *file* pointer to FILE structure representing the output file

← *format* format specification in standard printf-like form

← *modulo*

**See also:**

lawritemat()

### 3.6.3.15 `template<typename T> void LA::NRVec< T >::fscanf (FILE *f, const char *format)` [inline]

routine for formatted input

routine for formatted input via fscanf

#### Parameters:

- ← *f* pointer to FILE structure representing the input file
- ← *format* format specification in standard printf-like form

### 3.6.3.16 `template<> void LA::NRVec< complex< double > >::gemv (const complex< double > beta, const NRSMat< complex< double > > &A, const char trans, const complex< double > alpha, const NRVec< complex< double > > &x)` [inline]

perform the `gemv` operation on this complex vector  $\vec{y}$ , i.e.

$$\vec{y} \leftarrow \alpha op(A) \cdot \vec{x} + \beta \vec{y}$$

#### Parameters:

- ← *beta* complex parameter  $\beta$
- ← *A* **complex Hermitian** matrix *A* stored in packed form
- ← *trans* not used
- ← *alpha* complex parameter  $\alpha$
- ← *x* complex vector  $\vec{x}$

#### See also:

`gemm`, [NRSMat<T>](#)

### 3.6.3.17 `template<> void LA::NRVec< complex< double > >::gemv (const double beta, const NRSMat< double > &A, const char trans, const double alpha, const NRVec< complex< double > > &x)` [inline]

perform the `gemv` operation on this complex vector  $\vec{y}$ , i.e.

$$\vec{y} \leftarrow \alpha op(A) \cdot \vec{x} + \beta \vec{y}$$

#### Parameters:

- ← *beta* real parameter  $\beta$
- ← *A* **real symmetric** matrix *A* stored in packed form
- ← *trans* if `trans == 'n'` use *A* directly, otherwise  $op(A) \equiv A^T$
- ← *alpha* real parameter  $\alpha$
- ← *x* complex vector  $\vec{x}$

#### See also:

`gemm`, [NRSMat<T>](#)

**3.6.3.18** `template<> void LA::NRVec< double >::gemv (const double beta, const NRSMat< double > & A, const char trans, const double alpha, const NRVec< T > & x)`  
`[inline]`

perform the **gemv** operation on this real vector  $\vec{y}$ , i.e.

$$\vec{y} \leftarrow \alpha op(A) \cdot \vec{x} + \beta \vec{y}$$

**Parameters:**

- ← *beta* real parameter  $\beta$
- ← *A* real symmetric matrix *A* stored in packed form
- ← *trans* if `trans == 'n'` use *A* directly, otherwise  $op(A) \equiv A^T$
- ← *alpha* real parameter  $\alpha$
- ← *x* real vector  $\vec{x}$

**See also:**

`gemm`, [NRSMat<T>](#)

**3.6.3.19** `template<> void LA::NRVec< complex< double > >::gemv (const complex< double > beta, const NRMat< complex< double > > & A, const char trans, const complex< double > alpha, const NRVec< complex< double > > & x)` `[inline]`

perform the **gemv** operation on this complex vector  $\vec{y}$ , i.e.

$$\vec{y} \leftarrow \alpha op(A) \cdot \vec{x} + \beta \vec{y}$$

**Parameters:**

- ← *beta* complex parameter  $\beta$
- ← *A* **complex** matrix *A*
- ← *trans* if `trans == 'n'` use *A* directly, otherwise  $op(A) \equiv A^T$
- ← *alpha* complex parameter  $\alpha$
- ← *x* real vector  $\vec{x}$

**See also:**

`gemm`

**3.6.3.20** `template<> void LA::NRVec< complex< double > >::gemv (const double beta, const NRMat< double > & A, const char trans, const double alpha, const NRVec< complex< double > > & x)` `[inline]`

perform the **gemv** operation on this complex vector  $\vec{y}$ , i.e.

$$\vec{y} \leftarrow \alpha op(A) \cdot \vec{x} + \beta \vec{y}$$

**Parameters:**

- ← *beta* real parameter  $\beta$
- ← *A* real matrix  $A$
- ← *trans* if `trans == 'n'` use  $A$  directly, otherwise  $op(A) \equiv A^T$
- ← *alpha* real parameter  $\alpha$
- ← *x* real vector  $\vec{x}$

**See also:**

`gemm`

**3.6.3.21** `template<> void LA::NRVec< double >::gemv (const double beta, const NRMAT< double > &A, const char trans, const double alpha, const NRVec< T > &x)`  
`[inline]`

perform the **gemv** operation on this real vector  $\vec{y}$ , i.e.

$$\vec{y} \leftarrow \alpha op(A) \cdot \vec{x} + \beta \vec{y}$$

**Parameters:**

- ← *beta* real parameter  $\beta$
- ← *A* real matrix  $A$
- ← *trans* if `trans == 'n'` use  $A$  directly, otherwise  $op(A) \equiv A^T$
- ← *alpha* real parameter  $\alpha$
- ← *x* real vector  $\vec{x}$

**See also:**

[NRMAT<T>::gemm](#)

**3.6.3.22** `template<typename T> void LA::NRVec< T >::gemv (const T beta, const NRSMAT< T > &a, const char trans, const T alpha, const NRVec< T > &x)`

**Parameters:**

*trans* just for compatibility reasons

**3.6.3.23** `template<typename T > void LA::NRVec< T >::get (int fd, bool dim = 1, bool transp = 0)` `[inline]`

routine for unformatted input

routine for raw input

**Parameters:**

← *fd* file descriptor for input

← *dim* number of elements intended for input, for dim=0 perform copyonwrite

← *transp* reserved

See also:

[NRMAT<T>::get\(\), copyonwrite\(\)](#)

### 3.6.3.24 `template<typename T> GPUID LA::NVec< T >::getlocation () const` [inline]

routines for CUDA related stuff

- `getlocation()` gets the protected data member location
- `moveto(const GPUID)` moves underlying data between CPU/GPU memory

### 3.6.3.25 `template<> const double LA::NVec< complex< double > >::norm () const` [inline]

for this complex vector  $\vec{x}$  (of  $N$  elements) determine the Frobenius norm

Returns:

$$\sum_{i=1}^N |\vec{x}_i|^2$$

### 3.6.3.26 `template<> const double LA::NVec< double >::norm () const` [inline]

for this real vector  $\vec{x}$  (of  $N$  elements) determine the Frobenius norm

Returns:

$$\sum_{i=1}^N |\vec{x}_i|^2$$

### 3.6.3.27 `template<> NVec< complex< double > > & LA::NVec< complex< double > >::normalize (double * norm)` [inline]

normalize current complex vector (in the Euclidean norm)

Parameters:

← *norm* if not NULL, the norm of this vector is stored into \*norm

Returns:

reference to the modified vector

**3.6.3.28** `template<> NRVec< double > & LA::NRVec< double >::normalize (double * norm)`  
`[inline]`

normalize current real vector (in the Euclidean norm)

**Parameters:**

← *norm* if not NULL, the norm of this vector is stored into \*norm

**Returns:**

reference to the modified vector

**3.6.3.29** `template<typename T > LA::NRVec< T >::operator const T * () const` `[inline]`

get the constant pointer to the underlying data structure

get the constant pointer to the underlying data of this vector

**Returns:**

constant pointer to the first vector element

**3.6.3.30** `template<typename T > LA::NRVec< T >::operator T * ()` `[inline]`

get the pointer to the underlying data structure

get the pointer to the underlying data of this vector

**Returns:**

pointer to the first vector element

**3.6.3.31** `template<> const complex< double > LA::NRVec< complex< double > >::operator* (const NRVec< complex< double > > & rhs) const` `[inline]`

computes the inner product of this complex vector  $\vec{x}$  with given complex vector  $\vec{y}$  taking conjugation of vector  $\vec{x}$  into account

**Parameters:**

← *rhs* complex vector  $\vec{y}$

**Returns:**

$$\sum_{i=1}^N \vec{x}_i \cdot \vec{y}_i$$

**3.6.3.32** `template<> const double LA::NRVec< double >::operator* (const NRVec< double > & rhs) const` `[inline]`

computes the inner product of this real vector  $\vec{x}$  with given real vector  $\vec{y}$

**Parameters:**

← *rhs* real vector  $\vec{y}$

**Returns:**

$$\sum_{i=1}^N \vec{x}_i \cdot \vec{y}_i$$

**3.6.3.33** `template<typename T> const T LA::NRVec< T >::operator* (const NRVec< T > & rhs)`  
**const** [inline]

compute the Euclidean inner product (with conjugation in complex case)

compute scalar product  $d$  of this vector  $\vec{x}$  of general type  $T$  with given vector  $\vec{y}$  of type  $T$  and order  $N$

$$d = \sum_{i=1}^N \vec{x}_i \cdot \vec{y}_i$$

**Parameters:**

← *rhs* general vector  $\vec{y}$

**Returns:**

reference to the modified vector

**3.6.3.34** `template<> NRVec< complex< double > > & LA::NRVec< complex< double > >`  
`>::operator*= (const complex< double > & a)` [inline]

multiplies this complex vector  $\vec{x}$  by a complex scalar value  $\alpha$

$$\vec{x}_i \leftarrow \alpha \vec{x}_i$$

**Parameters:**

← *a* complex scalar value  $\alpha$

**Returns:**

reference to the modified vector

**3.6.3.35** `template<> NRVec< double > & LA::NRVec< double >::operator*= (const double & a)`  
[inline]

multiplies this real vector  $\vec{x}$  by a real scalar value  $\alpha$

$$\vec{x}_i \leftarrow \alpha \vec{x}_i$$

**Parameters:**

← *a* real scalar value  $\alpha$

**Returns:**

reference to the modified vector

**3.6.3.36** `template<typename T> NRVec< T > & LA::NRVec< T >::operator*=(const T & a)`  
`[inline]`

multiply this general vector  $\vec{x}$  by scalar value  $\lambda$

$$\vec{x}_i \leftarrow \lambda \vec{x}_i$$

**Parameters:**

$\leftarrow a$  scalar value  $\lambda$

**Returns:**

reference to the modified vector

**3.6.3.37** `template<typename T > NRVec< T > & LA::NRVec< T >::operator*=(const NRVec<`  
`T > & rhs) [inline]`

multiplies this vector  $\vec{y}$  componentwise by general vector  $\vec{x}$

$$\vec{x}_i = \vec{x}_i \times \vec{y}_i$$

**Parameters:**

$\leftarrow rhs$  general vector  $\vec{y}$

**Returns:**

reference to the modified vector

**3.6.3.38** `template<> NRVec< complex< double > > & LA::NRVec< complex< double >`  
`>::operator+=(const NRVec< complex< double > > & rhs) [inline]`

adds a complex vector  $\vec{y}$  to this complex vector  $\vec{x}$

$$\vec{x} \leftarrow \vec{x} + \vec{y}$$

**Parameters:**

$\leftarrow rhs$  complex vector  $\vec{y}$

**Returns:**

reference to the modified vector



### 3.6.3.39 `template<> NVec< double > & LA::NVec< double >::operator+=(const NVec< double > & rhs)` [inline]

adds a real vector  $\vec{y}$  to this real vector  $\vec{x}$

$$\vec{x} \leftarrow \vec{x} + \vec{y}$$

#### Parameters:

$\leftarrow$  *rhs* real vector  $\vec{y}$

#### Returns:

reference to the modified vector

### 3.6.3.40 `template<> NVec< complex< double > > & LA::NVec< complex< double > >::operator+=(const complex< double > & a)` [inline]

adds a complex scalar value  $\alpha$  to all elements of this complex vector  $\vec{x}$

$$\vec{x}_i \leftarrow \vec{x}_i + \alpha$$

#### Parameters:

$\leftarrow$  *a* complex scalar value  $\alpha$  being added

#### Returns:

reference to the modified vector

### 3.6.3.41 `template<> NVec< double > & LA::NVec< double >::operator+=(const double & a)` [inline]

routine for moving vector data between CPU and GPU memory

#### Parameters:

$\leftarrow$  *dest* required location

#### See also:

`NVec<T>::location`, `NVec<T>::getlocation()` adds a real scalar value  $\alpha$  to all elements of this real vector  $\vec{x}$

$$\vec{x}_i \leftarrow \vec{x}_i + \alpha$$

#### Parameters:

$\leftarrow$  *a* real scalar value  $\alpha$  being added

#### Returns:

reference to the modified vector

**3.6.3.42** `template<typename T> NRVec< T > & LA::NRVec< T >::operator+=(const T & a)`  
`[inline]`

bunch of scalar-vector arithmetic operators defined element-wise

adds given scalar value of type T to all vector elements

**Parameters:**

← *a* scalar value being added

**Returns:**

reference to the modified vector

**3.6.3.43** `template<typename T > NRVec< T > & LA::NRVec< T >::operator+=(const NRVec<`  
`T > & rhs) [inline]`

bunch of vector-vector arithmetic operators defined element-wise

adds a vector  $\vec{y}$  of general type T to this vector  $\vec{x}$

$$\vec{x} \leftarrow \vec{x} + \vec{y}$$

**Parameters:**

← *rhs* vector  $\vec{y}$  of type T

**Returns:**

reference to the modified vector

**3.6.3.44** `template<> const NRVec< complex< double > > LA::NRVec< complex< double >`  
`>::operator- () const [inline]`

unary minus operator in case of complex double-precision vector

**Returns:**

the modified vector by value

**3.6.3.45** `template<> const NRVec< double > LA::NRVec< double >::operator- () const`  
`[inline]`

unary minus operator in case of real double-precision vector

**Returns:**

the modified vector by value

**3.6.3.46** `template<typename T > const NRVec< T > LA::NRVec< T >::operator- () const`  
`[inline]`

unary minus

unary minus operator for vector of general type

**Returns:**

the modified vector

**3.6.3.47** `template<> NRVec< complex< double > > & LA::NRVec< complex< double > >::operator-= (const NRVec< complex< double > > & rhs)` `[inline]`

subtracts a complex vector  $\vec{y}$  from this complex vector  $\vec{x}$

$$\vec{x} \leftarrow \vec{x} - \vec{y}$$

**Parameters:**

$\leftarrow$  *rhs* double-precision complex vector  $\vec{y}$

**Returns:**

reference to the modified vector

**3.6.3.48** `template<> NRVec< double > & LA::NRVec< double >::operator-= (const NRVec< double > & rhs)` `[inline]`

subtracts a real vector  $\vec{y}$  from this real vector  $\vec{x}$

$$\vec{x} \leftarrow \vec{x} - \vec{y}$$

**Parameters:**

$\leftarrow$  *rhs* real vector  $\vec{y}$

**Returns:**

reference to the modified vector

**3.6.3.49** `template<> NRVec< complex< double > > & LA::NRVec< complex< double > >::operator-= (const complex< double > & a)` `[inline]`

subtracts a complex scalar value  $\alpha$  from all elements of this complex vector  $\vec{x}$

$$\vec{x}_i \leftarrow \vec{x}_i - \alpha$$

**Parameters:**

← *a* complex scalar value  $\alpha$  being subtracted

**Returns:**

reference to the modified vector

**3.6.3.50** `template<> NRVec< double > & LA::NRVec< double >::operator-= (const double & a)`  
`[inline]`

subtracts a real scalar value  $\alpha$  from all elements of this real vector  $\vec{x}$

$$\vec{x}_i \leftarrow \vec{x}_i - \alpha$$

**Parameters:**

← *a* real scalar value  $\alpha$  being subtracted

**Returns:**

reference to the modified vector

**3.6.3.51** `template<typename T> NRVec< T > & LA::NRVec< T >::operator-= (const T & a)`  
`[inline]`

subtracts given scalar value of type T from all vector elements

**Parameters:**

← *a* scalar value being subtracted

**Returns:**

reference to the modified vector

**3.6.3.52** `template<typename T > NRVec< T > & LA::NRVec< T >::operator-= (const NRVec<`  
`T > & rhs) [inline]`

subtracts given vector  $\vec{y}$  from this vector  $\vec{x}$

$$\vec{x}_i = \vec{x}_i - \vec{y}_i$$

**Parameters:**

← *rhs* vector  $\vec{y}$

**Returns:**

reference to the modified vector

### 3.6.3.53 `template<typename T> NRVec< T > & LA::NRVec< T >::operator/= (const NRVec< T > & rhs)` [inline]

divides this vector  $\vec{y}$  componentwise by general vector  $\vec{x}$

$$\vec{x}_i = \vec{x}_i / \vec{y}_i$$

#### Parameters:

← *rhs* general vector  $\vec{y}$

#### Returns:

reference to the modified vector

### 3.6.3.54 `template<typename T> const bool LA::NRVec< T >::operator< (const NRVec< T > & rhs) const` [inline]

comparison operator (lexicographical order)

#### Parameters:

← *rhs* vector intended for comparison

#### Returns:

- `false` current vector is bigger than vector *rhs*
- `true` current vector is smaller than vector *rhs*

### 3.6.3.55 `template<> NRVec< complex< double > > & LA::NRVec< complex< double > >::operator= (const complex< double > & a)` [inline]

assign complex scalar value to every element of the current vector

#### Parameters:

← *a* scalar value to be assigned

#### Returns:

reference to the modified vector

### 3.6.3.56 `template<> NRVec< double > & LA::NRVec< double >::operator= (const double & a)` [inline]

assign real scalar value to every element of the current vector

#### Parameters:

← *a* scalar value to be assigned

#### Returns:

reference to the modified vector

**3.6.3.57** `template<typename T> NRVec< T > & LA::NRVec< T >::operator= (const T & a)`  
`[inline]`

assignment operator assigns given scalar to each element of this vector

assign scalar value to every element of the current vector of general type T

**Parameters:**

← *a* scalar value to be assigned

**Returns:**

reference to the modified vector

**3.6.3.58** `template<typename T > NRVec< T > & LA::NRVec< T >::operator= (const NRVec< T`  
`> & rhs) [inline]`

assignment operator assigns given vector

assigns general vector  $\vec{y}$  to this vector  $\vec{x}$

- checks for self-assignment
- decreases the reference count and performs deallocation if necessary
- links the internal data structures with corresponding properties of vector  $\vec{y}$
- updates the reference count properly

**3.6.3.59** `template<typename T > const bool LA::NRVec< T >::operator> (const NRVec< T > &`  
`rhs) const [inline]`

comparison operator (lexicographical order)

**Parameters:**

← *rhs* vector intended for comparison

**Returns:**

- `true` current vector is bigger than vector *rhs*
- `false` current vector is smaller than vector *rhs*

**3.6.3.60** `template<typename T > const T & LA::NRVec< T >::operator[] (const int i) const`  
`[inline]`

indexing operator giving the element at given position with range checking in the DEBUG mode

**Parameters:**

← *i* position of the required vector element (starting from 0)

**Returns:**

constant reference to the requested element

**3.6.3.61** `template<typename T> T & LA::NVec< T >::operator[] (const int i) [inline]`

indexing operator - index running from zero

indexing operator giving the element at given position with range checking in the DEBUG mode

**Parameters:**

← *i* position of the required vector element (starting from 0)

**Returns:**

reference to the requested element

**3.6.3.62** `template<typename T> NVec< T > & LA::NVec< T >::operator|= (const NVec< T > & rhs) [inline]`

perform deep-copy of given vector

perform deep copy

**Parameters:**

← *rhs* vector being copied

**See also:**

[NVec<T>::copyonwrite\(\)](#)

**3.6.3.63** `template<> const NMat< complex< double > > LA::NVec< complex< double > >::otimes (const NVec< complex< double > > & b, const bool conj, const complex< double > & scale) const [inline]`

computes the outer product of this complex vector  $\vec{a}$  with given complex vector  $\vec{b}$  and scales the resulting matrix with factor  $\alpha$ , i.e. the matrix elements of the final matrix  $A$  can be expressed as

$$A_{i,j} = \alpha \cdot \vec{a}_i \vec{b}_j$$

in case `conj = true`, the result is

$$A_{i,j} = \alpha \cdot \vec{a}_i \vec{b}_j^*$$

**Parameters:**

← *b* complex vector  $\vec{b}$

← *conj* determines whether the vector  $\vec{b}$  is conjugated

← *scale* complex scaling factor  $\alpha$

**3.6.3.64** `template<> const NMat< double > LA::NVec< double >::otimes (const NVec< double > & b, const bool conj, const double & scale) const [inline]`

computes the outer product of this real vector  $\vec{a}$  with given real vector  $\vec{b}$  and scales the resulting matrix with factor  $\alpha$ , i.e. the matrix elements of the final matrix  $A$  can be expressed as

$$A_{i,j} = \alpha \cdot \vec{a}_i \vec{b}_j$$

**Parameters:**

- ← *b* real vector  $\vec{b}$
- ← *conj* not used
- ← *scale* real factor  $\alpha$

**3.6.3.65** `template<typename T> void LA::NRVec< T >::put (int fd, bool dim = 1, bool transp = 0) const` [inline]

routine for unformatted output

routine for raw output

**Parameters:**

- ← *fd* file descriptor for output
- ← *dim* number of elements intended for output
- ← *transp* reserved

**See also:**

[NRMat<T>::put\(\)](#)

**3.6.3.66** `template<> void LA::NRVec< complex< double > >::randomize (const double & x)` [inline]

fill the complex vector with pseudorandom numbers generated using uniform distribution the real and imaginary parts are generated independently

**Parameters:**

- ← *x* specification of the interval  $[0, x]$  for the random number generator

**Returns:**

- `false` current vector is bigger than vector `rhs`
- `true` current vector is smaller than vector `rhs`

**3.6.3.67** `template<> void LA::NRVec< double >::randomize (const double & x)` [inline]

fill the real vector with pseudorandom numbers generated using uniform distribution

**Parameters:**

- ← *x* specification of the interval  $[0, x]$  for the random number generator

**3.6.3.68** `template<typename T> void LA::NRVec< T >::resize (const int n)` [inline]

resize the current vector

resizes this vector

**Parameters:**

- ← *n* requested size



**3.6.3.69** `template<typename T> int LA::NVec< T >::size () const` `[inline]`

determine the number of elements

determine the number of elements of this vector

**Returns:**

length of this vector

**3.6.3.70** `template<typename T> const NVec< T > LA::NVec< T >::unitvector () const`  
`[inline]`

get normalized copy of this vector

create normalized copy of this vector

**Returns:**

copy of this vector after normalization

**See also:**

[NVec<T>::normalize\(\)](#)

The documentation for this class was generated from the following files:

- vec.h
- sparsemat.cc
- vec.cc

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